

NOTES:

1. MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS

2. STANDARD PRODUCT USES BI-DIRECTIONAL FAN. OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE.

3. KEY DIMENSIONS EQUAL

0.75x0.75x5.62

(MOTOR SUPPLIED WITH KEY)

TOSHIBA RESERVES THE RIGHT TO MAKE CHANGES OF TECHNICAL IMPROVEMENT AND THE DATA MAY CHANGE WITHOUT NOTICE

PRELIMINARY

DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED

X CERTIFIED

TOSHIBA www.toshiba.com/tic



TOTALLY ENCLOSED FAN COOLED
HORIZONTAL FOOT MOUNT
3 PHASE INDUCTION MOTOR
404T/405T F1 ASSEMBLY

DRAWING #: MDSLV081-08

REV. DATE: 8/17/17 REV. #: 3 PER.: J. HOCK

REV. DESCRIP.: CHANGED DRAWING TABLE FORMAT

TOSHIBA INTERNATIONAL CORPORATION



Issued Date	9/24/2019	Transmit #	
Issued By	dschoeck	Issued Rev	

TYPICAL MOTOR PERFORMANCE DATA

Model: 1004XDSC41A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
100	75	4	1775	405T	575	60	3	94
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	95.4	В	G	40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	100	74.6	93.6	95.7	83.5
¾ Load	75.00	55.9	74.5	95.2	79.1
½ Load	50.00	37.3	57.6	93.7	69.3
¼ Load	25.00	18.6	45.1	88.7	46.8
No Load			34.3		3.5
Locked Rotor			580		37.1

Torque						
Full Load	Locked Rotor	Pull Up	Break Down	Inertia		
(lb-ft)	(% FLT)	(% FLT)	(% FLT)	(lb-ft²)		
296	235	185	335	25.95		

Safe Stall	afe Stall Time(s) Sound		Bearin	Bearings*	
Cold	Hot	Pressure	<u>-</u>		Approx. Motor Weight
		dB(A) @ 1M	DE	NDE	(Ibs)
17	9	75	6317C3TMB	6313C3	

*Bearings are the only recommended spare part(s).

Tag:

Motor Options: Mounting:Footed,Shaft:T Shaft

Customer	
Customer PO	
Sales Order	
Project #	

All characteristics are av	All characteristics are average expected values.								
TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.									
Engineering	bmammen	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 1				
Engr. Date	11/15/2018	Doc. Approved By	M. Campbell	Doc. Issued	9/20/2019				



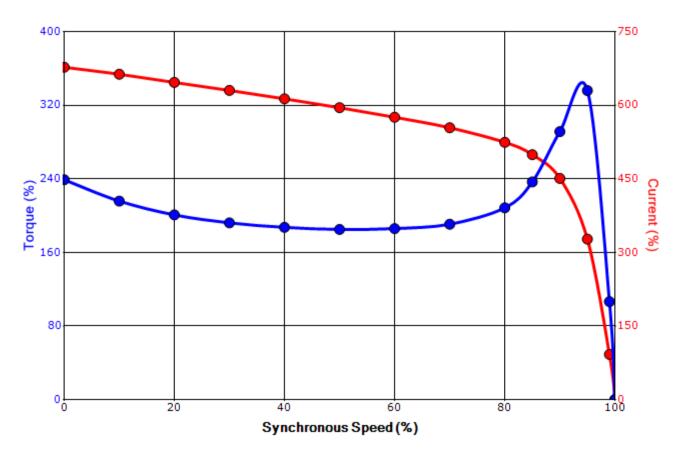
Issued Date	9/24/2019	Transmit #	
Issued By	dschoeck	Issued Rev	

SPEED TORQUE/CURRENT CURVE

Model: 1004XDSC41A-P

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
100	75	4	1775	405T	575	60	3	94
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	95.4	В	G	40 C
Laskad Datas	Rotor wk²	Torque						
Amps	Locked Rotor Inertia Full Load Locked Rotor		l Rotor	Pull Up		Break Down		
Amps	(lb-ft²)	(lb-ft)	(%	6)	(%)		(%	%)
580	25.95	296	235		185		335	

Design Values



Torque Current

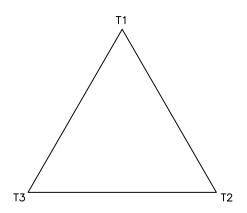
Customer	wk² Load Inerti	a (lb-ft²)
Customer PO	Lo	ad Type
Sales Order	Vol	age (%) 100
Project #	Acc	el. Time

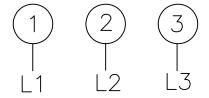
Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.								
Engineering	bmammen	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121/1			
Engr. Date	11/15/2018	Doc. Approved By	M. Campbell	Doc. Issued	9/20/2019			

Motor Connection Diagram 3 Leads - Delta Connection





Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable. If multiple cables represent a single lead, each one of them will be labeled with the appropriate lead number.

By: R. Murillo Date: 4/9/08 Checked: MDC Date: 5/17/11 Revision 0