

# Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS

Motor type: **GP100A** FS: **184T - 4p - 5 hp -**

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project
Remarks		

## Electrical data

U [V]	$\Delta/Y$	f [Hz]	P [HP]	P [kW]	n [rpm]	I Load [Amps]					LRC	Nom. Eff Load [%]			Pwr. Factor Load [%]			Torque [lb-ft]	T <sub>A</sub> /T <sub>N</sub> LRT [%]	T <sub>k</sub> /T <sub>N</sub> BDT [%]
						4/4	3/4	1/2	0	4/4		3/4	2/4	4/4	3/4	2/4				
575	Y	60	5.00	4.00	1,800	5.20	4.20	3.30	2.40	36.8	89.5	90.0	89.2	80.5	75.1	63.6	15.0	220	353	
Frame Type: 184T		Type of constr.: (A) Foot mounted - End shield				Ins. Cl.: Standard Class F Insulation		Motor Prot.: (A) Without Protection			NEMA Des.: B		S.F.: 1.15							
Mtr. WT: 70						Temp. Rise Cl.: B		Amb. Temp.: + 40 to -20 °C @1000 m			kVA: J		IP 55							

## Mechanical data

Sound level (SPL / SWL) at 60 Hz	57.0 dB(A) / 67.0 dB(A)		Thickener	Polyurea					
Octave Band Center Frequencies Hertz			Safe Stall Time Hot	14 s					
	250	500	1000	2000	4000	8000	Hz	Safe Stall Time Cold	29 s
SPL@3	42.0	46.0	54.0	49.0	43.0	32.0	dB(A)	Frame material	aluminum
Moment of inertia	0.3 Lb-ft <sup>2</sup>		Color, paint shade	Standard Paint - RAL7030					
Ext Load Inertia Capability:	27.0 Lb ft <sup>2</sup>		Coating (paint finish)	Standard Alkyed + Epoxy (C2)					
<b>Bearings</b>			<b>Ventilation Type</b>						
Bearing DE   NDE	6206 ZZ C3 S0		6206 ZZ C3 S0						
Bearing_Type	Ball Bearing		Ball Bearing						
AFBMA:	30BC02JPP30		30BC02JPP30						
<b>Grease</b>			Method of cooling						
Capacity	0.2 oz		0.2 oz						
Grease Type:	Exxon Mobile EM		Direction of rotation						
			Fan Material						
			VFD						
			Space heaters						
			Brake:						
			CT: 4:1 VT: 20:1						
			without						
			without						


## Terminal box

Lead Wire Connection		3 LEAD - WYE			Terminal box position	(3) F-1, Standard Floor Mount, T. Box LHS
Voltage	L1	L1	L1	Connected together	Material of terminal box	Aluminium
----	----	----	----	----	Cable entry	.75" NPT
----	T1	T2	T3	----		

## Notes:

I<sub>L</sub>/I<sub>N</sub> = locked rotor current / current nominal  
M<sub>L</sub>/M<sub>N</sub> = locked rotor torque / torque nominal  
M<sub>B</sub>/M<sub>N</sub> = break down torque / nominal torque

3) Value is valid only for DOL operation with motor design IC411  
2) at rated power / at full load

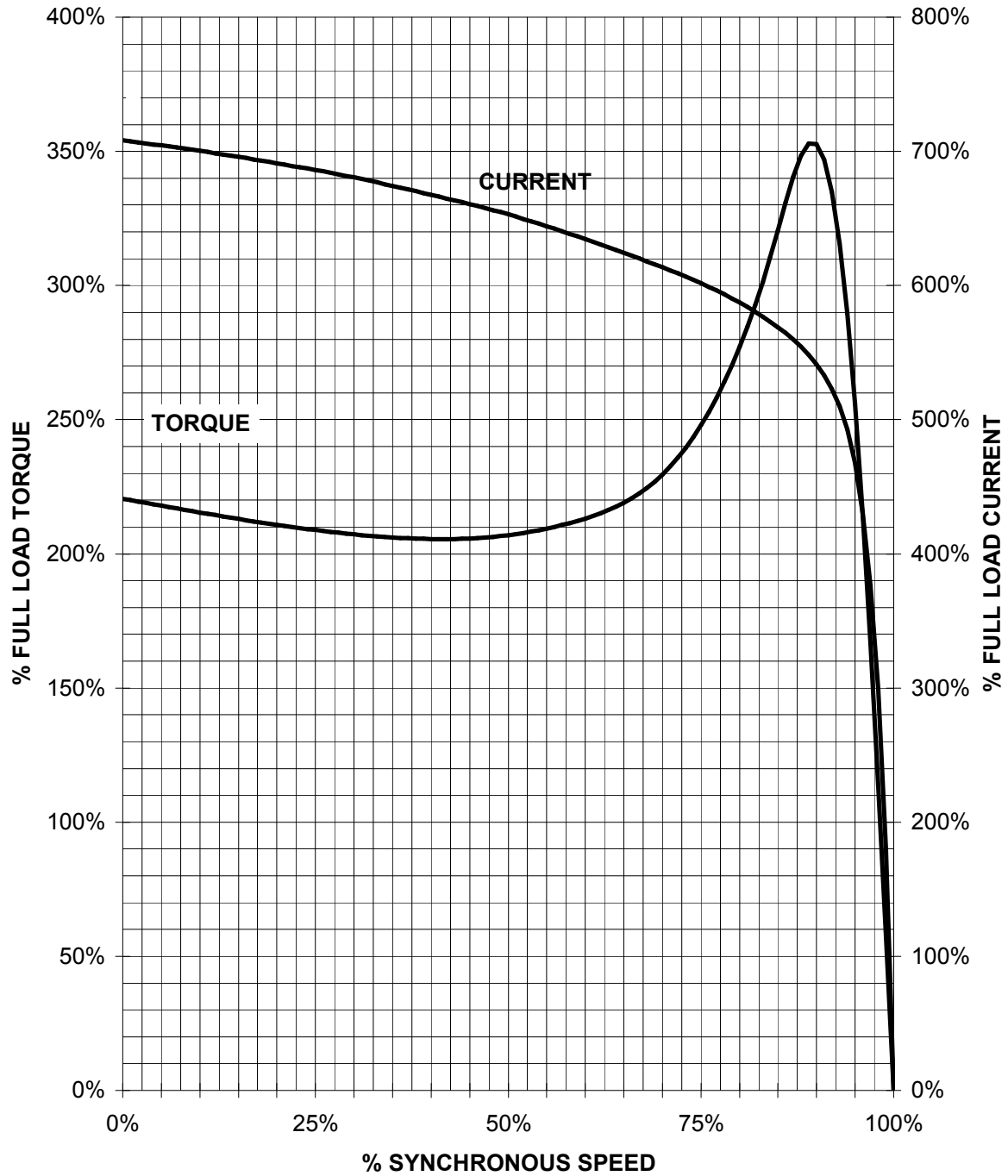
responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	<i>Technical data are subject to change! There may be discrepancies between datasheet and motor nameplate</i>	
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HP 5 VOLTS < 600V RPM 1800 TYPE GP100A  
HZ 60 PHASE 3 FRAME 184T NEMA B

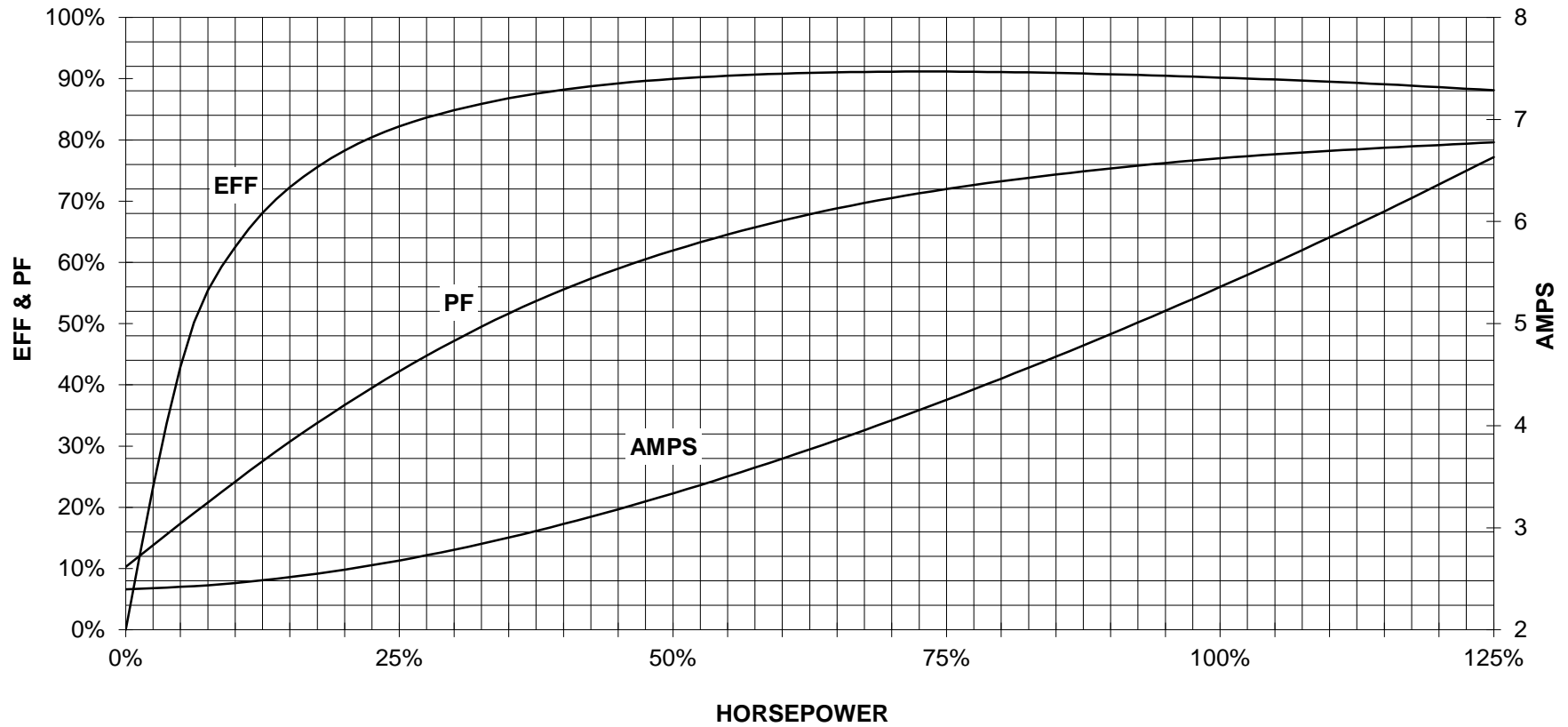
## TORQUE & CURRENT VS. SPEED



CUSTOMER: \_\_\_\_\_ ORDER#: \_\_\_\_\_

5 HP 1800 RPM 184 FRAME 575 VOLTS 3 PHASE NEMA DESIGN B

**SIEMENS INDUSTRY, INC.**  
**PERFORMANCE CURVE**  
**GP100A NP**

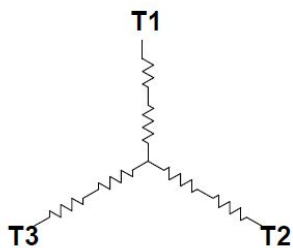


CUSTOMER \_\_\_\_\_ ORDER # \_\_\_\_\_ PO # \_\_\_\_\_


PERFORMANCE BASED ON DESIGN CALCULATIONS. SUBJECT TO CHANGE WITHOUT NOTICE.

REV. 1

Main terminal diagram



3 LEAD WYE			
LINES			CONN.
L1	L2	L3	
T1	T2	T3	Y

responsible dep. DI MC LVM	technical reference	created by	approved by	Project		
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