

# Data sheet for three-phase Squirrel-Cage-Motors SIMOTICS

**Motor type:** SD100 IEEE **FS: 254T - 2p - 15 hp -**

Client order no.	Item-No.	Offer no.
Order no.	Consignment no.	Project
Remarks		

## Electrical data

**Class I Division 2 Gr. A, B, C or D, T3**

U [V]	$\Delta/Y$	f [Hz]	P [HP]	P [kW]	n [rpm]	I Load [Amps]					LRC	Nom. Eff Load [%]			Pwr. Factor Load [%]			Torque [lb-ft]	T <sub>A</sub> /T <sub>N</sub> LRT [%]	T <sub>k</sub> /T <sub>N</sub> BDT [%]
						4/4	3/4	1/2	0	4/4		3/4	2/4	4/4	3/4	2/4				
460	Y	60	15.00	11.00	3,600	17.50	13.20	9.60	5.10	116.0	91.0	91.3	90.7	88.2	87.4	80.6	22.0	209	259	

Frame Type: 254T	Type of constr.: (A) Foot mounted - End shield	Ins. Cl.: Standard Class F Insulation	Motor Prot.: (A) Without Protection	NEMA Des.: B	S.F.: 1.15
Mtr. WT: 331		Temp. Rise Cl.: B	Amb. Temp.: + 40 to -20 °C @1000 m	kVA: G	IP 55


## Mechanical data

Sound level (SPL / SWL) at 60 Hz	70.0 dB(A) / 79.0 dB(A)							Thickener	Polyurea
Octave Band Center Frequencies Hertz								Safe Stall Time Hot	24 s
	250	500	1000	2000	4000	8000	Hz	Safe Stall Time Cold	48 s
SPL@3	60.0	73.0	72.0	75.0	69.0	56.0	dB(A)	Frame material	cast iron
Moment of inertia	1.1 Lb-ft <sup>2</sup>							Color, paint shade	Standard Paint - RAL7030
Ext Load Inertia Capability:	16.0 Lb ft <sup>2</sup>							Coating (paint finish)	Standard Alkyed + Epoxy (C2)
<b>Bearings</b>								<b>Ventilation Type</b>	
Bearing DE   NDE	6309 Z C3 S0			6309 Z C3 S0				Method of cooling	TEFC
Bearing_Type	Ball Bearing			Ball Bearing				Direction of rotation	Bidirectional
AFBMA:	45BC03JP30			45BC03JP30				Fan Material	Polypropylen ESD
<b>Grease</b>								VFD	CT: 4:1 VT: 20:1
Capacity	0.5 oz			0.5 oz				Space heaters	without
Grease Type:	Exxon Mobile EM							Brake:	without

## Terminal box

Lead Wire Connection	3 LEAD - WYE				Terminal box position	(3) F-1, Standard Floor Mount, T. Box LHS
Voltage	L1	L1	L1	Connected together	Material of terminal box	Cast Iron
----	----	----	----	----	Cable entry	1.25" NPT
----	T1	T2	T3	----		

**Notes:**  
 $I_L/M_N$  = locked rotor current / current nominal  
 $M_L/M_N$  = locked rotor torque / torque nominal  
 $M_B/M_N$  = break down torque / nominal torque  
 3) Value is valid only for DOL operation with motor design IC411  
 2) at rated power / at full load

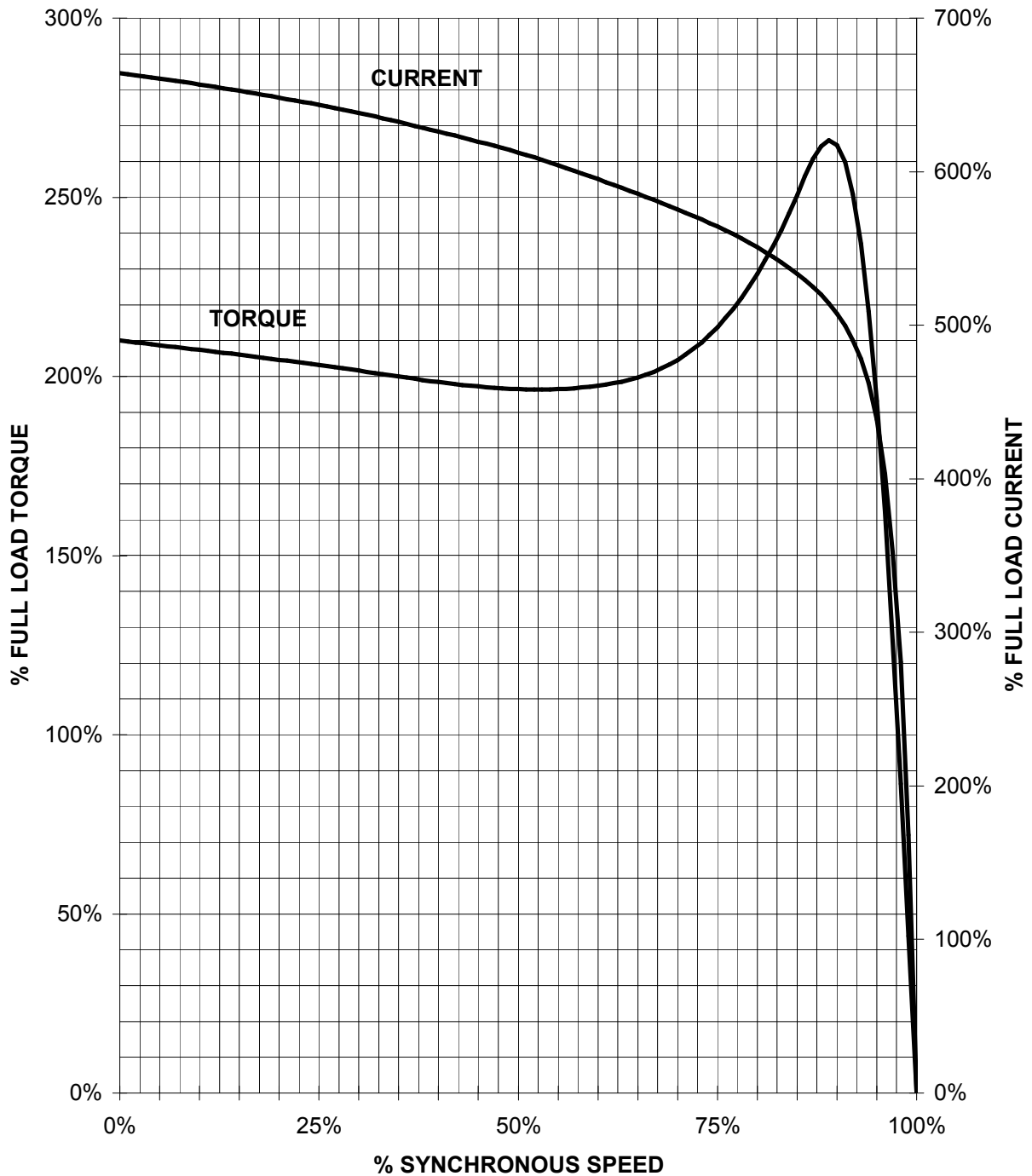
responsible dep. DI MC LVM	technical reference	created by DT Configurator	approved by	<i>Technical data are subject to change! There may be discrepancies between software and hardware versions</i>			
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HP 15 VOLTS < 600V RPM 3600 TYPE SD100 IEEE841  
HZ 60 PHASE 3 FRAME 254T NEMA B

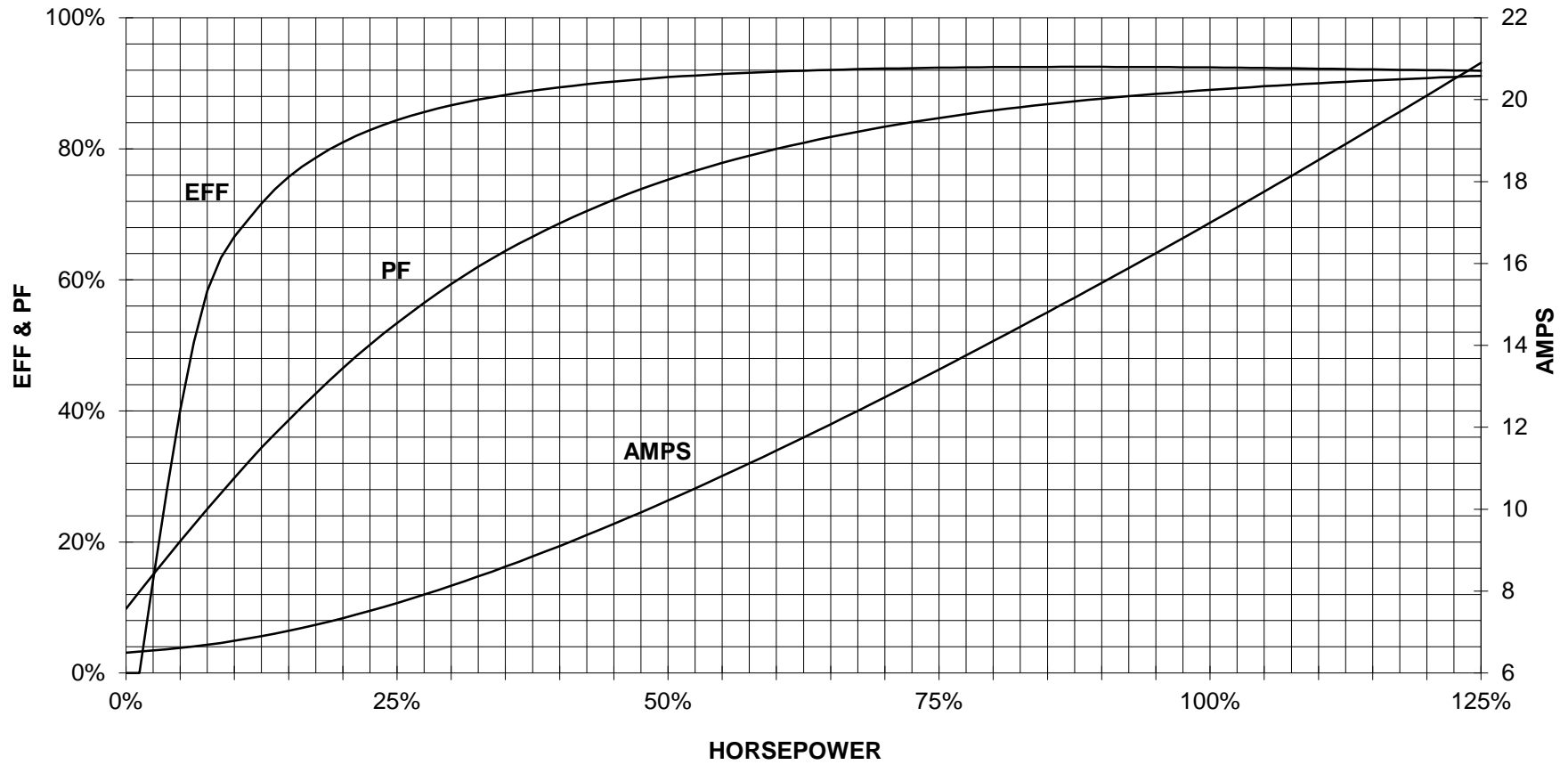
## TORQUE & CURRENT VS. SPEED



CUSTOMER: \_\_\_\_\_ ORDER#: \_\_\_\_\_

15 HP 3600 RPM 254T FRAME 460 VOLTS 3 PHASE NEMA DESIGN B

**SIEMENS INDUSTRY, INC.**  
**PERFORMANCE CURVE**  
**SD100 IEEE841**



CUSTOMER \_\_\_\_\_ ORDER # \_\_\_\_\_ PO # \_\_\_\_\_

PERFORMANCE BASED ON DESIGN CALCULATIONS. SUBJECT TO CHANGE WITHOUT NOTICE.

REV. 1

Main terminal diagram



3 LEAD WYE			
LINES			CONN.
L1	L2	L3	
T1	T2	T3	Y

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