

UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										
	A	B	C	D	G	J	K	M	O	P	T
B447TS/B449TS	22.0	38.9	56.8	11.00	1.4	4.5	17.7	23.3	25.1	27.9	1.3
B447T/B449T	22.0	38.9	60.5	11.00	1.4	4.5	17.7	23.3	25.1	27.9	1.3

FRAME SIZE	CONDUIT BOX											
	AA(NPT)	AB ₁	AB ₂	AC ₁	AC ₂	AE	AF ₁	AF ₂	XL ₁	XL ₂	XN ₁	XN ₂
B447/9T - B447/9TS	4.00	29.8	23.8	22.4	19.6	11.00	9.6	9.1	23.4	15.2	14.2	10.2

FRAME SIZE	MOUNTING				SHAFT EXTENSION				KEY SEAT				BEARINGS				MAXIMUM WEIGHT
	E	2F	H	BA	N-W	V	U	R	S	ES	LS ROLLER	LS BALL 6/8P	LS BALL 4P	OS 4-8P			
B447TS/B449TS	9.00	20.00/25.00	0.81	7.50	4.75	4.50	2.375	2.021	0.625	3.03	-	6318C3	6318C3	6318C3	4500 lbs.		
B447T/B449T	9.00	20.00/25.00	0.81	7.50	8.50	8.25	3.375	2.880	0.875	6.91	NU322C3	6322C3	6318C3	6318C3	4500 lbs.		

CUSTOMER: _____ MOTOR MODEL NO.: _____ TAG NO's: _____

P.O. NO.: _____ HP: _____ VOLTAGE: _____ RPM(STN.): _____ HZ: _____

FRAME SIZE: _____ PRODUCT TYPE: IEC EQP III SD & 841

COMMENTS: _____

PER: _____ DATE: _____

TOSHIBA RESERVES THE RIGHT TO MAKE CHANGES OF TECHNICAL IMPROVEMENT AND THE DATA MAY CHANGE WITHOUT NOTICE PRELIMINARY

DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED CERTIFIED

- STANDARD (NO AUX. BOXES)
- RTD AUX. BOX
- SPACE HEATER AUX. BOX
- BEARING RTD's

- NOTES:
- DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT.
 - MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS.
 - *TS* KEY DIMENSIONS EQUAL S x S x 3.00 (*TS* KEY DIMENSIONS EQUAL S x S x 6.88 (MOTOR SUPPLIED WITH KEY))
 - MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME.
 - THIS DIMENSION EQUALS 2F FOR B447T MOUNTING.
 - STANDARD PRODUCT USE BI-DIRECTIONAL FAN, OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE.
 - FRAME GROUND BOLT STANDARD ON 841 PRODUCT.
 - ONLY FOR 400HP/4 POLE/460V & 350HP/6 POLE/460V MOTORS.

TOSHIBA

TOTALLY-ENCLOSED FAN-COOLED
HORIZONTAL FOOT-MOUNTED
3 PHASE INDUCTION MOTOR
F1 ASSEMBLY

XT SERIES

VISIT OUR WEBSITE AT:
www.toshiba.com/ind

TOSHIBA INTERNATIONAL CORPORATION

TYPICAL MOTOR PERFORMANCE DATA

Model: 3006XDSB41A-R

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
300	224	6	1190	B449T	460	60	3	357
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	95.8	A		40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	300.00	223.7	356	95.7	82.2
¾ Load	225.00	167.8	279	95.1	79.2
½ Load	150.00	111.9	209	93.7	71.5
¼ Load	75.00	55.9	154	88.9	51.1
No Load			130.9		3.1
Locked Rotor			2396		22.8

Torque				Rotor wk ² Inertia (lb-ft ²)
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
1324	165	105	260	207.92

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
35	15	82	NU322C3	6318C3	

*Bearings are the only recommended spare part(s).

Motor Options:
Mounting:Footed,Shaft:T Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

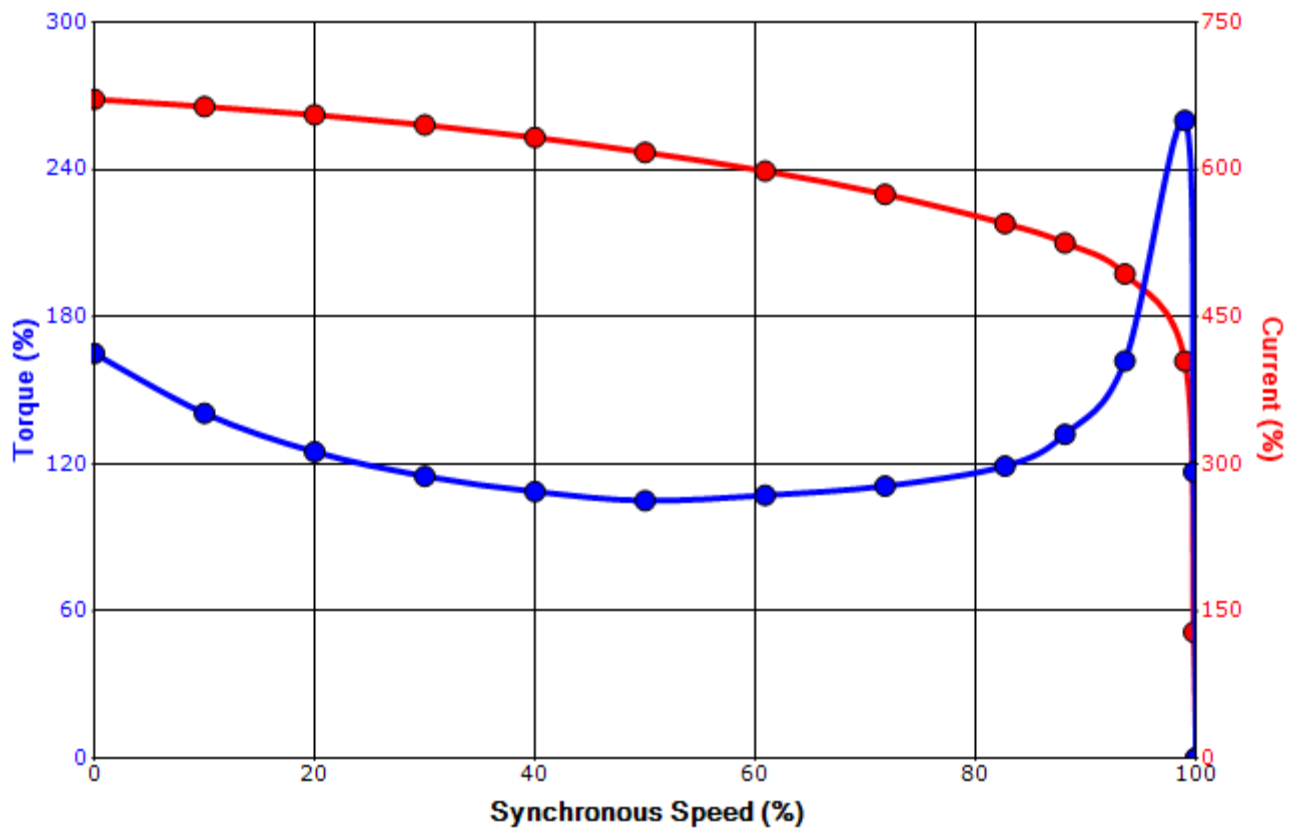
Engineering	SSuryani	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	12/23/2019	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

SPEED TORQUE/CURRENT CURVE

Model: 3006XDSB41A-R

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
300	224	6	1190	B449T	460	60	3	357
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	95.8	A		40 C
Locked Rotor Amps	Rotor wk ² Inertia (lb-ft ²)	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
2396	207.92	1324	165	105			260	

Design Values



Customer		wk ² Load Inertia (lb-ft ²)	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

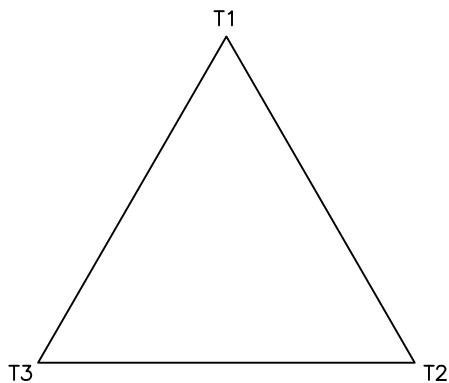
Tag:

All characteristics are average expected values.

TOSHIBA INTERNATIONAL CORPORATION · HOUSTON, TEXAS U.S.A.

Engineering	SSuryani	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	12/23/2019	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

Motor Connection Diagram
3 Leads - Delta Connection



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.
If multiple cables represent a single lead, each one
of them will be labeled with the appropriate lead number.