

UNITS: INCHES

FRAME SIZE	MOTOR DIMENSIONS										
	A	B	C	D	G	J	K	M	O	P	T
B447TS/B449TS	22.0	38.9	56.8	11.00	1.4	4.5	17.7	23.3	25.1	27.9	1.3
B447T/B449T	22.0	38.9	60.5	11.00	1.4	4.5	17.7	23.3	25.1	27.9	1.3

FRAME SIZE	CONDUIT BOX											
	AA(NPT)	AB <sub>1</sub>	AB <sub>2</sub>	AC <sub>1</sub>	AC <sub>2</sub>	AE	AF <sub>1</sub>	AF <sub>2</sub>	XL <sub>1</sub>	XL <sub>2</sub>	XN <sub>1</sub>	XN <sub>2</sub>
B447/9T - B447/9TS	4.00	29.8	23.8	22.4	19.6	11.00	9.6	9.1	23.4	15.2	14.2	10.2

FRAME SIZE	MOUNTING				SHAFT EXTENSION				KEY SEAT				BEARINGS				MAXIMUM WEIGHT
	E	2F	H	BA	N-W	V	U	R	S	ES	IS ROLLER	IS BALL 6/8P	IS BALL 4P	OS 4-8P			
B447TS/B449TS	9.00	20.00/25.00	0.81	7.50	4.75	4.50	2.375	2.021	0.625	3.03	-	6318C3	6318C3	6318C3	4500 lbs.		
B447T/B449T	9.00	20.00/25.00	0.81	7.50	8.50	8.25	3.375	2.880	0.875	6.91	NU322C3	6322C3	6318C3	6318C3	4500 lbs.		

CUSTOMER: \_\_\_\_\_ MOTOR MODEL NO.: \_\_\_\_\_ TAG NO's: \_\_\_\_\_

P.O. NO.: \_\_\_\_\_ HP: \_\_\_\_\_ VOLTAGE: \_\_\_\_\_ RPM(STN.): \_\_\_\_\_ HZ: \_\_\_\_\_

FRAME SIZE: \_\_\_\_\_ PRODUCT TYPE: IEC EQP III SD & 841

COMMENTS: \_\_\_\_\_

PER: \_\_\_\_\_ DATE: \_\_\_\_\_

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DO NOT USE FOR CONSTRUCTION, INSTALLATION, OR APPLICATION PURPOSES UNLESS THE DRAWING IS MARKED AS CERTIFIED  CERTIFIED

- STANDARD (NO AUX. BOXES)
- RTD AUX. BOX
- SPACE HEATER AUX. BOX
- BEARING RTD's

- NOTES:
- DIMENSION V REPRESENTS LENGTH OF STRAIGHT PART OF SHAFT.
  - MAIN CONDUIT BOX MAY BE ROTATED IN 90° INCREMENTS.
  - \*TS\* KEY DIMENSIONS EQUAL S x S x 3.00 (\*TS\* KEY DIMENSIONS EQUAL S x S x 6.88 (MOTOR SUPPLIED WITH KEY))
  - MOTOR WEIGHT SHOWN IS MAXIMUM HORSEPOWER IN FRAME.
  - THIS DIMENSION EQUALS 2F FOR B447T MOUNTING.
  - STANDARD PRODUCT USE BI-DIRECTIONAL FAN, OPPOSITE ROTATION AVAILABLE ONLY BY CONNECTION CHANGE.
  - FRAME GROUND BOLT STANDARD ON 841 PRODUCT.
  - ONLY FOR 400HP/4 POLE/460V & 350HP/6 POLE/460V MOTORS.

**TOSHIBA**

TOTALLY-ENCLOSED FAN-COOLED  
HORIZONTAL FOOT-MOUNTED  
3 PHASE INDUCTION MOTOR  
F1 ASSEMBLY

**XT SERIES**

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**TYPICAL MOTOR PERFORMANCE DATA**

Model: 3006XSSB41A

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
300	224	6	1190	B449T	460	60	3	357
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	95.8	A		40 C

Load	HP	kW	Amperes	Efficiency (%)	Power Factor (%)
Full Load	300.00	223.7	356	95.7	82.2
¾ Load	225.00	167.8	279	95.1	79.2
½ Load	150.00	111.9	209	93.7	71.5
¼ Load	75.00	55.9	154	88.9	51.1
No Load			130.9		3.1
Locked Rotor			2397		22.8

Torque				Rotor wk <sup>2</sup> Inertia (lb-ft <sup>2</sup> )
Full Load (lb-ft)	Locked Rotor (% FLT)	Pull Up (% FLT)	Break Down (% FLT)	
1324	165	105	260	207.92

Safe Stall Time(s)		Sound Pressure dB(A) @ 1M	Bearings*		Approx. Motor Weight (lbs)
Cold	Hot		DE	NDE	
35	15	82	6322C3	6318C3	

\*Bearings are the only recommended spare part(s).

**Motor Options:**  
Product Family:EQP Global 840  
Mounting:Footed,Shaft:T Shaft

Customer	
Customer PO	
Sales Order	
Project #	

Tag:

All characteristics are average expected values.

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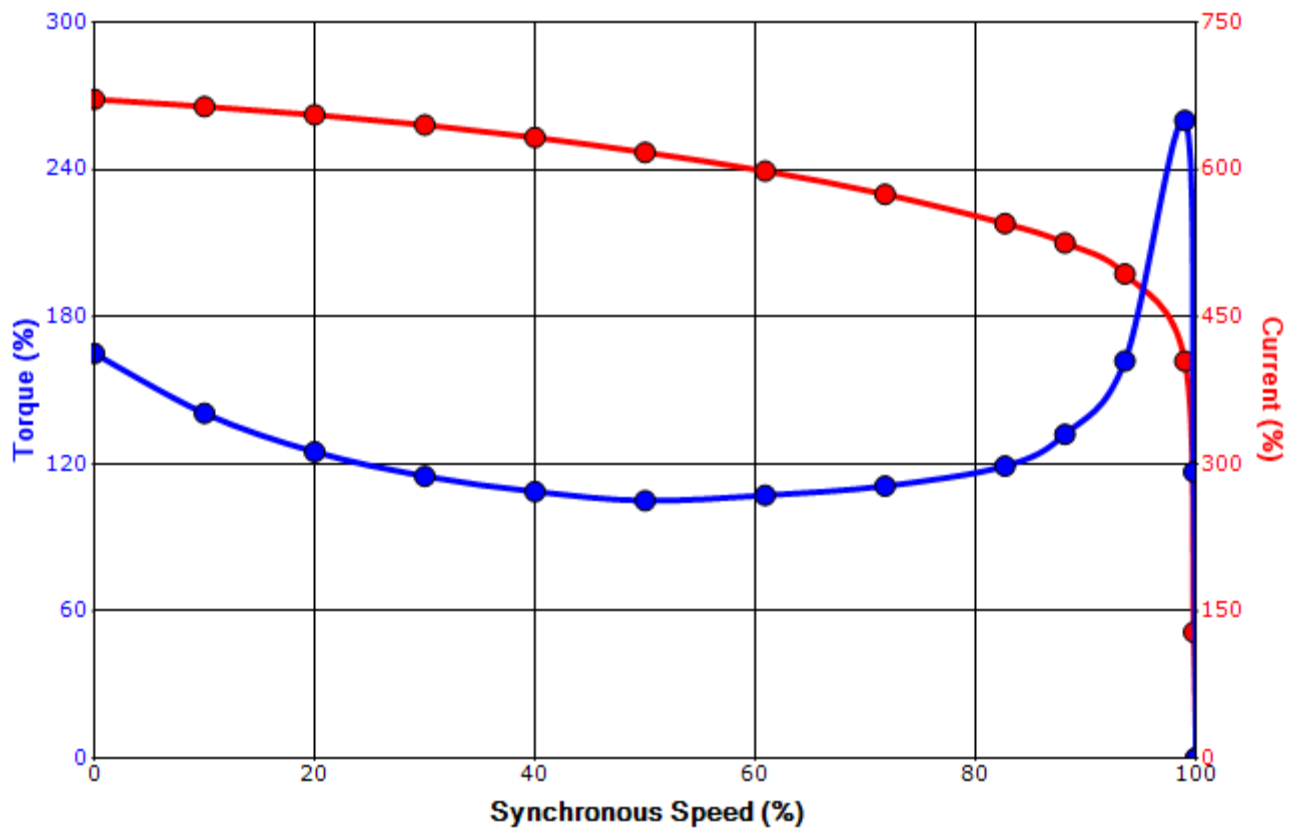
Engineering	SSuryani	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1119 / 0
Engr. Date	12/23/2019	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

**SPEED TORQUE/CURRENT CURVE**

Model: 3006XSSB41A

HP	kW	Pole	FL RPM	Frame	Voltage	Hz	Phase	FL Amps
300	224	6	1190	B449T	460	60	3	357
Enclosure	IP	Ins. Class	S.F.	Duty	NEMA Nom. Eff.	NEMA Design	kVA Code	Ambient (°C)
TEFC	56	F	1.15	CONT	95.8	A		40 C
Locked Rotor Amps	Rotor wk <sup>2</sup> Inertia (lb-ft <sup>2</sup> )	Torque						Break Down (%)
		Full Load (lb-ft)	Locked Rotor (%)	Pull Up (%)				
2397	207.92	1324	165	105			260	

**Design Values**



Customer		wk <sup>2</sup> Load Inertia (lb-ft <sup>2</sup> )	-
Customer PO		Load Type	-
Sales Order		Voltage (%)	100
Project #		Accel. Time	-

Tag:

All characteristics are average expected values.

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Engineering	SSuryani	Doc. Written By	D. Suarez	Doc.# / Rev	MPCF-1121 / 0
Engr. Date	12/23/2019	Doc. Approved By	M. Campbell	Doc. Issued	6/8/2011

### Motor Connection Diagram 3 Leads - Delta Connection



Switch L1 and L2 to reverse rotation

Each lead may consist of more than one cable.  
If multiple cables represent a single lead, each one  
of them will be labeled with the appropriate lead number.