NIDEC MOTOR CORPORATION

8050 WEST FLORISSANT AVE. ST. LOUIS, MO 63136



DATE: 4/19/2022 **P.O. NO**.: DT37

Order/Line NO.: 22214 MN 100

TO:

Model Number:DT37REVISIONS:Catalog Number:HJ25P2GM(NONE)

Hostile Duty CCP Configuration CONF,MOTOR,HOSTILE DUTY CCP

ALL DOCUMENTS HEREIN ARE CONSIDERED CERTIFIED BY NIDEC MOTOR CORPORATION. THANK YOU FOR YOUR ORDER AND THE OPPORTUNITY TO SERVE YOU.

Features:

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Horsepower ...... 00025.00 ~ KW: 18.65
Enclosure ..... TEFC
Poles ..... 04 ~ RPM: 1800
Frame Size ..... 284~JM
Phase/Frequency/Voltage.. 3~060~575 ~ Random Wound
Service Factor ..... 1.15
Insulation Class ...... Class "F" ~ Insulife 1000
Altitude In Feet (Max) .. 3300 Ft.(1000 M)
Ambient In Degree C (Max) +40 C
Assembly Position ..... "F-1" Assembly Position
Efficiency Class ...... Premium Efficiency
Application ...... Close Coupled Pump
Customer Part Number ....
"AK" Dimension (Inches).. 12.500
Temperature Rise (Sine Wave): "B" Rise @ 1.0 SF (Resist)
Starting Method ..... Direct-On-Line Start
Duty Cycle ..... Continuous Duty
Efficiency Value ..... 92.4 % ~ Typical
Load Inertia (lb-ft2): NEMA ~ NEMA Inertia: 122.00 ~ 1.00
Number Of Starts Per Hour: NEMA
Motor Type Code ..... CTE4
Rotor Inertia (LB-FT<sup>2</sup>)
                              3.55 LB-FT<sup>2</sup>
Qty. of Bearings PE (Shaft)
                             1
                             1
Qty. of Bearings SE (OPP)
Bearing Number PE (Shaft)
                            6311-J/C3
                             6310-2Z-J/C3
Bearing Number SE (OPP)
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Accessories:

USE THE DATA PROVIDED BELOW TO SELECT THE APPROPRIATE DIMENSION PRINT

 Horsepower
 25

 Pole(s)
 04

 Voltage(s)
 575

 Frame Size
 284JM

 Shaft U Diameter
 1.250

 Outlet Box AF
 3.25

 Outlet Box AA
 2.00

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EFFECTIVE: 13-JUN-11

SUPERSEDES: 16-FEB-09

HORIZONTAL MOTORS

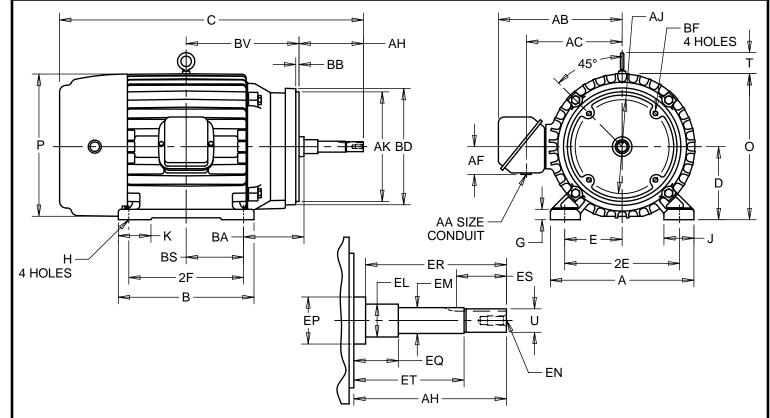
CLOSED COUPLED PUMP FRAME: 284, 286JM **BASIC TYPE: CT-4**

PRINT:

07-2783

SHEET:

1 OF 1



ALL DIMENSIONS ARE IN INCHES AND MILLIMETERS

UNITS	Α	В	С	D 06	Е	2E ±.03	G	H +.05	J	0	P ²
IN	13.75	13.00	27.88	7.00	5.50	11.00	1.00	.53	2.88	14.28	14.50
ММ	349	330	708	178	140	279	25	13	73	363	368

	UNITS	Т	U 0005	AA	AB	AC	AF	AH ±.031	AJ	AK 005	ВА	BB MIN	BD MAX
	IN	2.06	1.2495	2.00	13.07	9.69	3.25	5.250	11.000	12.500	4.75	.31	14.00
Г	MM	52	31.737	2.00	332	246	83	133.35	279.40	317.50	121	8	356

UNITS	BF	BV	EL 002	EM 0005	EN	EP MIN	EQ ±.020	ER MIN	ES MIN	ET ±.020	EV	SQ KEY
IN	5/0.44 V 04	10.50	1.750	1.3750	4/0.40 V.4.00	2.13	.625	5.25	2.53	3.000	1.00	.250
MM	5/8-11 X .94	267	44.45	34.925	1/2-13 X 1.00	54	15.88	133	64	76.20	25	6.35

FRAME	UNITS	2F ±.03
004 IM	IN	9.50
284 JM	MM	241
	IN	11.00
286 JM	MM	279

TOLERANCES	
FACE RUNOUT	.007 T.I.R.
PERMISSIBLE ECCENTRICITY OF MOUNTING RABBET	.007 T.I.R.
PERMISSIBLE SHAFT RUNOUT	.003 T.I.R.

^{1:} ALL ROUGH CASTING DIMENSIONS MAY VARY BY .25" DUE TO CASTING AND/OR FABRICATION VARIATIONS.

^{2:} LARGEST MOTOR WIDTH.

^{3:} TOLERANCES SHOWN ARE IN INCHES ONLY.

^{4:} STANDARD ASSEMBLY POSITION F-1 IS SHOWN F-2 IS PROVIDED WHEN SPECIFIED. CONDUIT OPENINGS MAY BE LOCATED IN STEPS OF 90°REGARDLESS OF LOCATION. STANDARD AS SHOWN WITH CONDUIT OPENING DOWN.

^{5:} ALL TAPPED HOLES ARE UNIFIED NATIONAL COARSE, RIGHT HAND THREAD.

^{6:} TAP SIZE AND BOLT PENETRATION ALLOWANCE.

NAMEPLATE DATA

CATALOG NUMBER:	HJ25P2GM	NAMEPLATE PART #:	422696-002
MODEL DT37	FR 284JM	TYPE CTE4	ENCL TE
SHAFT END BRG	6311-J/C3 - QTY 1	OPP END BRG	6310-2Z-J/C3 - QTY 1
	AX 40 C	ID#	
INSUL F As	m. F1	DUTY	CONT
HP 25	RPM 1775	HP ====================================	RPM 💳 💳
VOLTS 575		VOLTS	
FL 23.0		FL AMPS	
SF AMPS 26.6		SF AMPS	
SF 1.15 DESIG	GN B CODE G		GN CODE
NEMA NOM 036 NOM		NEMA NOM NOM PF	1
CHARANTEED MAY	,	GUARANTEED MAX EFFICIENCY KVAI	
EFFICIENCY 92.4 KVAF		EFFICIENCY KVAI	`
HAZARDOUS LOCATION DATA (IF AIDIVISION ESSENTING TEMP CODE	CLASS I E	GROUGROU GROUGR	
FD DATA (IF APPLICABLE):			
VOLTS ======		AMPS	
TORQUE 1		TORQUE 2	
		VFD LOAD TYPE 2 VFD HERTZ RANGE 2	
VFD SPEED RANGE 1		VFD SPEED RANGE 2	
SERVICE FACTOR		FL SLIP	
NO. POLES	4	MAGNETIZING AMPS	6.5
VECTOR MAX RPM		Encoder PPR	
Radians / Seconds	1	Encoder Volts	
EAO DATA (IF APPLICABLE):	LID (AID OVED	DDM (AID	
HP (AIR OVER)	HP (AIR OVER M/S)	RPM (AIR OVER)	RPM (AIR OVER
FPM AIR VELOCITY	FPM AIR VELOCITY M/S	FPM AIR VELOCITY SEC	

ADDITIONAL NAMEPLATE DATA:

Notes	Decal / Plate	WD=499495	Customer PN	
Max Temp Rise				
Thermal (WDG)		80C PISE/PES@1 00SE		GPEASE
Regulatory Notes	<u> </u>	000 NI3E/NE3@1.0031		
Regulatory Notes COS Marine Duty Balance Arctic Duty Motor Weight (LBS) 380 Direction of Rotation Sound Level Vertical Thrust (LBS) Sound Level Vertical Thrust (LBS) Special Note 2 Thrust Percentage Bairing Life Special Note 3 Special Note 3 Special Note 3 Special Note 5 Number of Starts Special Note 6 Special Note 8 Special Note 9 Special Note 1 Special Note 9 Note 1 Note 1 Note 1 Note 1 Note 1 Note 10				GILAGE
COS				CC 030A
Balance				CC 030A
Motor Weight (LBS) Motor Weight (LBS) Motor Weight (LBS) Sound Level Vertical Thrust (LBS) First Percentage Bearing Life Starting Method Number of Starts 200/208V 60Hz Max Amps 380V 50 Hz Max Amps MEMA Inertia Sumpheater Voltage Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 5 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 24 Special Accessory Note 10 Special Accessory Note 20 Special Accessory Note 20 Special Accessory Note 21 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 1 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 6 Special Accessory Note 20 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 9 Special Accessory Note 10 Special Accessory Note 23 Special Accessory Note 24 Special Accessory Note 11 Special Accessory Note 12 Special Accessory Note 25 Special Accessory Note 25 Special Accessory Note 10 Special Accessory Note 27 Special Accessory Note 10 Special Accessory Note 27 Special Accessory Note 10 Special Accessory Note 28 Special Accessory Note 29 Special Accessory Note 3 Special Accessory Note 28 Special Accessory Note 29 Special Accessory Note 30 Special Accessory Note 30 Special Accessory Note 30 Special Accessory Note 30 Special Accessory Note				
Motor Weight (LBS) Sound Level Special Note 1 Special Note 2 Thrust (LBS) Special Note 2 Thrust Percentage Special Note 3 Bearing Life Starting Method Special Note 5 Number of Starts Special Note 6 200/208V 60Hz Max Amps SH Wats SH Wats SH Wats SH Wats NEMA Inertia Sumpheater Voltage Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 5 Special Accessory Note 5 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 9 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 9 Special Accessory Note 2 Special Accessory Note 10 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 13 Special Accessory Note 14 Special Accessory Note 15 Special Accessory Note 15 Special Accessory Note 16 Special Accessory Note 17 Special Accessory Note 18 Special Accessory Note 19 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 20 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 20 Special Accessory Note 10 Special Accessory Note 20 Sp		04.2		
Sound Level				
Vertical Thrust (LBS) Thrust Percentage Bearing Life Special Note 3 Bearing Life Starting Method Special Note 5 Number of Starts Special Note 6 200/2087 60/14- Max Amps SH Watts SH Watts NEMA Inertia Sumpheater Voltage Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 3 Special Accessory Note 4 Special Accessory Note 5 Special Accessory Note 5 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 8 Special Accessory Note 8 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 8 Special Accessory Note 8 Special Accessory Note 2 Special Accessory Note 1 Special Accessory Note 5 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 1 Special Accessory Note 1 Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 3		360		
Thrust Percentage Special Note 3				
Bearing Life Starting Method Starting Method Starting Method Special Note 5 Number of Starts 200/208V 60Hz Max Amps SH Max. Temp. 190V 50 hz Max Amps SH Voltage 380V 50 Hz Max Amps SH Voltage Sumpheater Voltage Sumpheater Voltage Special Accessory Note 1 Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 3 Special Accessory Note 3 Special Accessory Note 4 Special Accessory Note 4 Special Accessory Note 5 Special Accessory Note 5 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 10 Special Accessory Note 9 Special Accessory Note 9 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 11 Special Accessory Note 12 Special Accessory Note 12 Special Accessory Note 11 Special Accessory Note 12 Special Accessory Note 12 Special Accessory Note 13 Special Accessory Note 14 Special Accessory Note 15 Special Accessory Note 15 Special Accessory Note 15 Special Accessory Note 15 Special Accessory Note 16 Special Accessory Note 17 Special Accessory Note 18 Special Accessory Note 19 Special Accessory Note 10 Special Accessory Note 11 Special Accessory Note 28 Special Accessory Note 15 Special Accessory Note 15 Special Accessory Note 16 Special Accessory Note 29 Special Accessory Note 15 Special Accessory Note 10 Note 1 Note 1 Note 1 Note 5 Note 6 Note 7 Note 9 Note 10 Note 10 Note 10 Note 10 Note 10	<u> </u>		<u> </u>	
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Number of Starts 200/208V 60Hz Max Amps 380V 50 Hz Max Amps SH Watts NEMA Inertia Load Inertia Sumpheater Voltage Special Accessory Note 1 Special Accessory Note 2 Special Accessory Note 3 Special Accessory Note 4 Special Accessory Note 4 Special Accessory Note 5 Special Accessory Note 5 Special Accessory Note 6 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 9 Special Accessory Note 9 Special Accessory Note 9 Special Accessory Note 1 Special Accessory Note 6 Special Accessory Note 7 Special Accessory Note 8 Special Accessory Note 8 Special Accessory Note 9 Special Accessory Note 9 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 10 Special Accessory Note 11 Special Accessory Note 12 Special Accessory Note 12 Special Accessory Note 13 Special Accessory Note 13 Special Accessory Note 13 Special Accessory Note 14 Special Accessory Note 15 Special Accessory Note 16 Special Accessory Note 17 Special Accessory Note 18 Special Accessory Note 19 Special Accessory Note 10 Special Accessory Note 27 Special Accessory Note 11 Special Accessory Note 27 Special Accessory Note 13 Special Accessory Note 28 Special Accessory Note 29 Special Accessory Note 29 Special Accessory Note 30 Heater in C/B Watts Ander 1 Note 1 Note 2 Note 3 Note 4 Note 5 Note 6 Note 7 Note 10			<u> </u>	
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Special Accessory Note 8 Special Accessory Note 23 Special Accessory Note 9 Special Accessory Note 24 Special Accessory Note 10 Special Accessory Note 25 Special Accessory Note 25 Special Accessory Note 26 Special Accessory Note 26 Special Accessory Note 27 Special Accessory Note 12 Special Accessory Note 27 Special Accessory Note 28 Special Accessory Note 13 Special Accessory Note 28 Special Accessory Note 29 Special Accessory Note 15 Special Accessory Note 30 Heater in C/B Voltage Heater in C/B Watts Zone 2 Group Division 2 Service Factor Note 1 Note 3 Note 4 Note 3 Note 4 Note 5 Note 6 Note 7 Note 9 Note 10 Note 10 Note 11 Note 12	Special Accessory Note 6		Special Accessory Note 21	
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Special Accessory Note 11 Special Accessory Note 26 Special Accessory Note 27 Special Accessory Note 13 Special Accessory Note 28 Special Accessory Note 28 Special Accessory Note 29 Special Accessory Note 29 Special Accessory Note 15 Special Accessory Note 30 Heater in C/B Voltage Heater in C/B Watts Zone 2 Group Division 2 Service Factor Note 1 Note 2 Note 3 Note 4 Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Special Accessory Note 9		Special Accessory Note 24	
Special Accessory Note 12 Special Accessory Note 13 Special Accessory Note 28 Special Accessory Note 29 Special Accessory Note 15 Special Accessory Note 29 Special Accessory Note 15 Special Accessory Note 30 Heater in C/B Voltage Heater in C/B Watts Zone 2 Group Division 2 Service Factor Note 1 Note 3 Note 3 Note 4 Note 5 Note 6 Note 7 Note 9 Note 10 Note 11 Note 12	Special Accessory Note 10		Special Accessory Note 25	
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Heater in C/B Voltage Heater in C/B Watts Zone 2 Group Division 2 Service Factor Note 1 Note 2 Note 3 Note 4 Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Special Accessory Note 14		Special Accessory Note 29	
Zone 2 Group Division 2 Service Factor Note 1 Note 2 Note 3 Note 4 Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Special Accessory Note 15		Special Accessory Note 30	
Note 1 Note 2 Note 3 Note 4 Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Heater in C/B Voltage		Heater in C/B Watts	
Note 3 Note 4 Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Zone 2 Group		Division 2 Service Factor	
Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Note 1		Note 2	
Note 5 Note 6 Note 7 Note 8 Note 9 Note 10 Note 11 Note 12	Note 3		Note 4	
Note 7 Note 8 Note 9 Note 10 Note 11 Note 12				
Note 9 Note 10 Note 11 Note 12				
Note 11 Note 12				
Note 13 Note 14	Note 13		Note 14	
Note 15 Note 16				
Note 17 Note 18				
Note 19 Note 20				
Note 21 Note 22				

NIDEC MOTOR CORPORATION

ST. LOUIS, MO

TYPICAL NAMEPLATE DATA
ACTUAL MOTOR NAMEPLATE LAYOUT MAY VARY
SOME FIELDS MAY BE OMITTED



MOTOR PERFORMANCE

MODEL NO.	CATALOG NO.	PHASE	TYPE	FRAME
DT37	HJ25P2GM	3	CTE4	284JM
ORD	ER NO.	22214	LINE	NO.
MPI:	'			129563
HP:				25
POLES:				4
VOLTS:				575
HZ:				60
SERVICE FACTO	R:			1.15
EFFICIENCY (%):				
		.F		93
		JLL		93.6
		/4		94.3
		/2		94
		/4		91
POWER FACTOR				
		.F.		87.2
		JLL		86.9
		/4		84.9
		/2		78.8
		/4		60.8
		OAD		6
	LOCKED	ROTOR		39.5
AMPS:				
		.F.		26.6
		JLL		23
		/4		17.6
		/2		12.6
		/4		8.5
		OAD		6.5
NEMA CODE LET		ROTOR		140
NEMA CODE LET				G
NEMA DESIGN LE	TIEK			B
FULL LOAD RPM	/ FEELCHENOV (0/)			1775
NEMA NOMINAL				93.6
GUARANTEED EF	FICIENCY (%)			92.4
MAX KVAR AMBIENT (°C)				5.5 40
ALTITUDE (FASL)	1			3300
SAFE STALL TIME				30
SOUND PRESSU				66
TORQUES:	TE (DDA @ 11VI)			
TOTAGOLO.	BREAKDO	WN{% F.L.}		259
		TOR{% F.L.}		194
		AD{LB-FT}		73.9
	1 OLL LOP	ייין וין וו		1,0.0

NEMA Nominal and Guaranteed Efficiencies are up to 3,300 feet above sea level and 25 ° C ambient

The Above Data Is Typical, Sinewave Power Unless Noted Otherwise

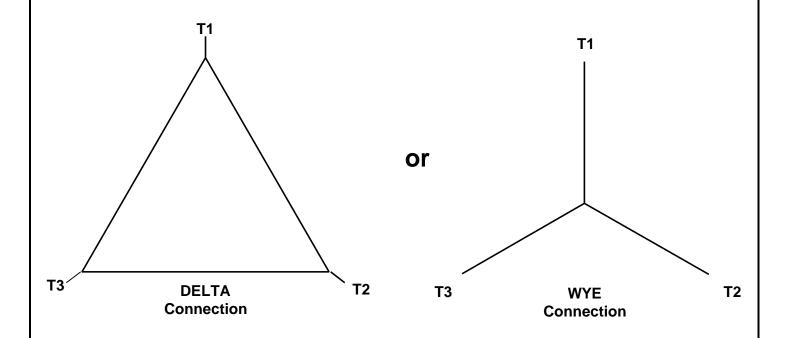
NIDEC MOTOR CORPORATION ST. LOUIS, MO

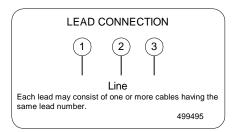






Motor Wiring Diagram



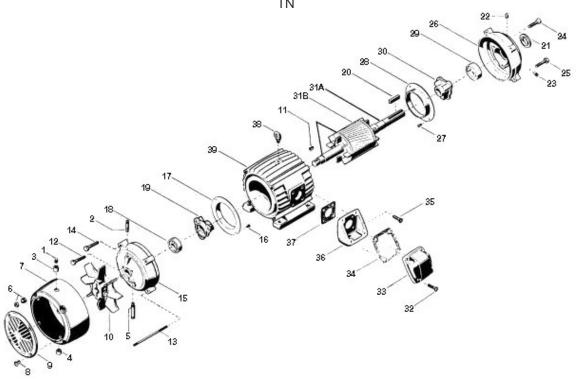


To reverse direction of rotation interchange connections L1 and L2.

Each lead may be comprised of one or more cables. Each cable will be marked with the appropriate lead number.

RENEWAL PARTS

FRAMES 254T THRU 447T, 449T (WORLD MOTOR) - TOTALLY ENCLOSED AND EXPLOSIONPROOF MOTORS TYPES: CE, CE1, CE4, CEF, CT, CT1, CT4, CTC, CTE, CTE1, CTE4, CTEF, CTEF1, CTEF4, CTEI, CTEN, CTF, CTF1, FCTN, FD, FDF, FDF1, FL, FLC, FLCA, FLCF, FLF, FN, FNC, FTC, FTCF, JAD, JDE, L, L1, L4, LC, LC1, LCA, LCAE, LCE, LCEF, LCE1, LCE1, LCF, LCF, LCF, LCI, LE1, LE4, LEF, LF, LF1, LF4, LFC, LF1, LI, LN, N, NC, NCE, NCEF, NCF, NCF1, NCI, NE, NF, NN, T, T1, T4, TC, TC1, TCA, TCA, TCE, TCE1, TCE4, TCEF4, TCEF4, TCEI, TCEN, TCEP, TCF1, TCF1, TCF1, TCI1, TCN, TE, TEF, TEN, TF, TFC, TFN,



ITEM NO.	QTY	NAME OF PART
1	1	Slotted Headless Pipe Plug
2	1	Pipe Coupling
3	1	Pipe Nipple
4	1	Pipe Cap
5	1	Pipe Nipple
6	2	Cap and Jam Nut
7	1	Fan Cover Guard
8	3	Screw & Lockwasher
9	1	Grill
10	1	Vent Fan Assembly
11	1	Woodruff Key (Not used on frames 254T &256T
12	2	Screw
13	2	Stud & Nut
14	2	Screw (Qty 6 on frames 254T & 256T)
15	1	Bracket
16	4	Screw (Used only on frame 286T & 326T)
17	1	Air Deflector (Used only on frame 286T & 326T)
18	1	Ball Bearing
19	1	Bearing Cap
20	1	Key
21	1	Water Deflector

ITEM NO.	QTY	NAME OF PART
22	1	Slotted Headless Pipe Plug
23	1	Pipe Plug
24	2	Screw
25	4	Screw (Qty 8 on frames 286T & 326T)
26	1	Bracket (Not used on types TF)
27	4	Screw (Used only on frame 286T & 326T)
28	1	Air Deflector ((Used only on frame 286T & 326T)
29	1	Ball Bearing
30	1	Bearing Cap
31	1	Rotor Assembly (Includes items 31A & 31B)
31A	1	Motor Shaft
31B	1	Rotor Core
32	4	Screw
33	1	Outlet Box Cover
34	1	Gasket
35	4	Screw (Qty 2 on frames 254T & 256T)
36	1	Outlet Box Base
37	1	Gasket (Outlet Box Base)
38	1	Eyebolt
39	1	Wound Stator Assembly

WARNING:

Any disassembly or repair work on explosion proof motors will void the Underwriters Laboratories, Inc. label unless done by the manufacturer, or a facility approved by the Underwriters Laboratories, Inc. Refer to your nearest sales office for assistance.

BEARINGS:

Refer to motor nameplate for the bearing numbers.

PRICES:

Parts stocking distributors: refer to renewal parts numerical index. All Others: refer to your nearest parts distributor.

reference: Renewal Parts Section 700, Page 19

General Information for Integral Horsepower (IHP) Motors on Variable Frequency Drives (VFDs)

Variable Frequency Drives (VFD)

A VFD is a type of controller used to vary the speed of an electric motor. The VFD takes a fixed AC voltage and frequency and allows it to be adjusted in order to get different speeds from the motor. Motor speed can be varied by changing the frequency of the input power waveform. The equation below shows how the frequency affects the speed of a three phase induction motor.

Speed =
$$\frac{120^* \text{ Fundamental Input Frequency}}{\text{Number of Motor Poles}}$$

How does a VFD work?

A VFD takes the fixed frequency and voltage sine wave from the power grid or power station and puts it through a few steps in order to allow the VFD user to vary the frequency and in turn control the motor speed. First it rectifies the AC power into DC Power. Because of this step, a term commonly used instead of VFD is inverter. This only describes one step of what the VFD does to the power waveform. Once rectified into a DC voltage the drive sends the power through a set of transistors or switches. These switches can take the DC waveform and by opening and closing at certain speeds and durations can create an output waveform that mimics the sine wave that is required to drive a three phase electric motor. The output wave form is known as a Pulse Width Modulation (PWM) waveform because the waveform is created by multiple pulses of the switches at short intervals.

PULSE WIDTH MODULATION WAVEFORM



What variables should be considered when deciding whether to power a motor with a VFD?

VFD compatibility with motors is complex. As a result, many variables must be considered when determining the suitability of a particular motor for use with a VFD. These variables include:

- Torque requirements (Constant or Variable)
- Speed Range
- Line / System Voltage
- Cable length between the VFD and the motor
- Drive switching (carrier) frequency
- Motor construction

- VFD dv/dt winding end turn differential in voltage versus differential in time
- · High temperatures or high humidity
- · Grouding system

Wider speed ranges, higher voltages, higher switching frequencies, insufficient grounding and increased cable lengths all add to the severity of the application and, therefore, the potential for premature motor failure.

How does a VFD affect the motor?

There are many things to consider when a motor is powered using a VFD or PWM power. When a motor is powered by a PWM waveform the motor windings very often see a large differential voltage, either from phase to phase or turn to turn. When the voltage differential becomes large enough it creates a reaction at the molecular level that converts available oxygen into O3. This phenomenon is called partial discharge or corona. This reaction creates energy in the form of light and heat. This energy has a corrosive effect on the varnish used to protect the motor windings. PWM waveforms can also magnify shaft voltages which lead to arcing across the bearing and causing premature bearing failure. Corrective action must be taken to mitigate these issues that arise when using an electric motor with a VFD.

How do I protect the motor?

Nidec Motor Corporation (NMC) has developed specific motor designs to decrease the harmful affects that a VFD can have on a motor. NMC's INVERTER GRADE® insulation system is the first line of defense against corona and phase to phase faults that can be common when a motor is powered using a PWM waveform. The INVERTER GRADE® insulation system is standard on all of NMC's Inverter Duty products. Along with the INVERTER GRADE® insulation, thermostats are installed as a minimum protection against over heating the motor. Special consideration must also be given to bearings in motors powered by VFD's. In order to create a low resistance path to ground for built up shaft voltages a shaft grounding device can be used. On larger horsepower motors an insulated bearing system should be used in conjunction with the shaft grounding device when installed, to force the stray shaft voltages to ground. The bearing failures are more prominent on motors with thrust handling bearings. NMC has created an Inverter Duty vertical motor line that not only uses the INVERTER GRADE® insulation system, but that also comes standard with a shaft grounding device. On motors that are 100 HP and greater the thrust bearing is also insulated for additional protection.

What does "Inverter Duty" mean?

An Inverter Duty motor should describe a motor that helps mitigate potential failure modes of a motor that is powered by a VFD. Inverter duty motor windings should be able to withstand the voltage spikes per NEMA MG1 Part 31.4.4.2 and protect against overheating when the motor is run at slow speeds. On thrust handling bearings it is apparent that the bearings require additional protection. Inverter Duty vertical motors should have a shaft grounding device to protect the motor bearings from fluting due to voltage discharge through the bearing. On larger motors (100HP and larger) the shaft should also be electrically isolated from the frame in order to aid the shaft grounding ring in discharging the shaft voltages to ground.

^{*}This information applies only to Integral Horsepower (IHP) motors as defined on the Agency Approval page, under UL® & CSA® listings where indicated.

Motor / Inverter Compatibility

Thermal Overloads and Single Phase Motors

Motors with thermal overloads installed may not operate properly on a VFD. The current carrying thermal overload is designed for sine wave power. Operation on a VFD may cause nuisance tripping or potentially not protect the motor as would be expected on line power. Thermostats or thermistors installed in the motor and connected properly to the VFD may provide suitable thermal overload protection when operating on a VFD. (consult codes for installation requirements)

Single phase motors and other fractional horsepower ratings are not designed to be operated on a VFD. Within Nidec Motor Corporation standard products, all motors NEMA® 148 frame (5.5" diameter) and smaller are not suitable for VFD applications. Three phase 56 and 143/145 frame applications should be noted on the catalog price page; or if in doubt ask a Nidec Motor Corporation technical representative for recommendations on compatibility with a VFD.

Slow Speed Motors

Motors with a base design of slower than six poles require special consideration regarding VFD sizing and minimizing harmonic distortion created at the motor terminals due to cable installation characteristics. Additional external PWM waveform filters and shielded motor cables designed for PWM power may be required to provide acceptable motor life. Harmonic distortion on the output waveform should be kept to a minimum level (less than 10%) mismatch impedance.

690V Applications

Motors that are rated for 690VAC and that will be powered by 690VAC PWM VFDs require the use of an external filter to limit peak voltage spikes and the use of an INVERTER GRADE® motor. Where available, an alternative to using an output filter is to upgrade to a 2300V insulation system.

Low Voltage TITAN® Motors

When using 449 frame and larger motors on PWM type VFDs consider the use of an external filter and shielded motor cables designed for PWM power to minimize harmonic distortion and peak voltages at the motor terminals. Harmonic distortion on the output waveform should be kept to a minimum level (less than 10%).

Bearing Currents Related to PWM Waveforms

Protection of the motor bearings from shaft currents caused by common mode voltages is becoming a standard feature on Inverter Duty motor products. Some installations may be prone to a voltage discharge condition through the motor bearings called Electrical Discharge Machining (EDM) or fluting. Vertical HOLLOSHAFT and HOSTILE DUTY World Motor come with grounding devices installed as standard. EDM damage is related to characteristics of the PWM waveform, and the VFD programming, and installations factors.

Bearing Protection on Inverter Duty Vertical Motors

All U.S. MOTORS® brand "Inverter Duty" vertical products have a shaft grounding system that allows damaging shaft currents a low resistance path to ground. **Bearings on vertical motors fed by VFD power without this bearing protection are not covered under any warranty.** All other bearing failure is covered per NMC's standard warranty. An electric motor repair shop approved to service U.S. MOTORS® brand motors must verify that the cause of the bearing failure was not due to EDM damage.

Guideline For Insulated Anti-Friction Bearings

Bearing insulation is required to prevent circulating shaft currents which can damage bearings. Circulating shaft current can be caused by use of improper power and/or ground cables, improper grounding systems and higher switching frequencies. Finding and correcting the external condition(s) is the responsibility of the system designer or specifying engineer. To prevent circulating shaft current in motors with anti-friction bearings, Nidec Motor Corporation's standard practice is to insulate the non-drive end bearing.

Adjustable Speed Drives produce a common mode voltage condition. To interrupt common mode voltage on induction motors of all sizes, NEMA MG1-2018 Part 31 recommends insulating both bearings. In cases where both anti-friction bearings are insulated, the system designer or specifying engineer should determine whether to apply one or more of the following options to prevent or reduce shaft currents: sinewave filters, line reactors or mechanical devices, such as shaft grounding or an insulated half coupling. Motors with shaft grounding devices are not suitable for installation in hazardous locations unless housed in an enclosure suitable for the specified Division (or Zone), Class and Group(s).

Multiple Motors on a Single VFD

Special considerations are required when multiple motors are powered from a single VFD unit. Most VFD manufacturers can provide guidelines for proper motor thermal considerations and starting/stopping of motors. Cable runs from the VFD and each motor can create conditions that will cause extra stress on the motor winding. Filters may be required at the motor to provide maximum motor life.

Grounding and Cable Installation Guidelines

Proper output winding and grounding practices can be instrumental in minimizing motor related failures caused by PWM waveform characteristics and installation factors. VFD manufacturers typically provide detailed guidelines on the proper grounding of the motor to the VFD and output cable routing. Cabling manufacturers provide recommended cable types for PWM installations and critical information concerning output wiring impedance and capacitance to ground.

Integrated Motor and Inverter

By integrating the motor and inverter at NMC's manufacturing facility, many of the motor compatibility problems are minimized or eliminated. During the manufacturing process, the motor is matched to the inverter characteristics which ensures the winding temperature and torque levels meet the design specification. Since the inverter output wiring to the motor is nearly eliminated, bearing currents are rarely experienced. When the unit is properly grounded, reducing the output cable lengths in conjunction with an inverter grade insulation system and low factory setting of the switching frequency of the inverter drive, results in low risk of voltage peaks produced by the PWM waveform.

Vertical Motors on VFDs

Vertical motors operated on VFD power present unique conditions that may require consideration by the user or installation engineer:

- Locked rotor and drive tripping caused by non-reversing-ratchet operation at low motor speeds. It is not recommended to operate motors at less than 1/4 of synchronous speed. If slow speeds are required contact NMC engineering.
- Unexpected / unacceptable system vibration and or noise levels caused by the
 torque pulsation characteristics of the PWM waveform, a system critical frequency
 falling inside the variable speed range of the process or the added harmonic content
 of the PWM waveform exciting a system component
- Application related problems related to the controlled acceleration/deceleration and torque of the motor on VFD power and the building of system pressure/ load.
- The impact the reduction of pump speed has on the down thrust reflected to the pump motor and any minimum thrust requirements of the motor bearings
- · Water hammer during shutdown damaging the non-reversing ratchet

Humidity and Non-operational Conditions

The possible build-up of condensation inside the motor due to storage in an uncontrolled environment or non-operational periods in an installation, can lead to an increased rate of premature winding or bearing failures when combined with the stresses associated with PWM waveform characteristics. Moisture and condensation in and on the motor winding over time can provide tracking paths to ground, lower the resistance of the motor winding to ground, and lower the Corona Inception Voltage (CIV) level of the winding.

Proper storage and maintenance guidelines are important to minimize the potential of premature failures. Space heaters or trickle voltage heating methods are the common methods for drying out a winding that has low resistance readings. Damage caused by these factors are not covered by the limited warranty provided for the motor unless appropriate heating methods are properly utilized during non-operational periods and prior to motor start-up.

NEMA® Application Guide for AC Adjustable Speed Drive Systems: http://www.nema.org/stds/acadjustable.cfm#download

www.usmotors.com viii

^{*} This information applies only to Integral Horsepower (IHP) motors as defined on the Agency Approval page, under UL*1 & CSA*1 listings where indicated.

Warranty Guidelines for Integral Horsepower (IHP)* Motors on Variable Frequency Drives

Warranty Guidelines

The information in the following section refers to the motor and drive application guidelines and limitations for warranty.

Hazardous Location Motors

Use of a variable frequency drive with the motors in this catalog, intended for use in hazardous locations, is only approved for Division1, Class I, Group D hazardous location motors with a T2B temperature code, with a limitation of 2:1 constant torque or 10:1 variable torque output. No other stock hazardous location motors are inherently suitable for operation with a variable frequency drive. If other requirements are needed, including non-listed Division 2, please contact your Nidec Motor Corporation territory manager to conduct an engineering inquiry.

575 Volt Motors

575 volt motors can be applied on Inverters when output filters are used. Contact the drive manufacturer for filter selection and installation requirements.

Applying INVERTER GRADE® Insulated Motors on Variable Frequency Drives (2, 4, 6 pole)

The products within this catalog labeled "Inverter Duty" or "Vector Duty" are considered INVERTER GRADE® insulated motors. INVERTER GRADE® motors exceed the NEMA®† MG-1 Part 31 standard. Nidec Motor Corporation provides a three-year limited warranty on all NEMA®† frame INVERTER GRADE® insulated motors and allows long cable runs between the motor and the VFD (limited to 400 feet without output filters). Cable distance can be further limited by hot and humid environments and VFD manufacturers cable limits. These motors may be appropriate for certain severe inverter applications or when the factors relating to the end use application are undefined (such as spares).

Nidec Motor Corporation's U.S. Motors® brand is available in the following INVERTER GRADE® insulated motors:

- Inverter Duty NEMA^{®†} frame motors good for 20:1 Variable Torque
 5:1 Constant Torque, including Vertical Type RUSI (10:1 V.T.)
- Inverter Duty motors rated for 20:1 Constant Torque
- ACCU-Torq® and Vector Duty Motors with full torque to 0 Speed or 5000:1
- 841 Plus® NEMA®† Frame Motors

Applying Premium Efficient motors (that do not have INVERTER GRADE® insulation) on Variable Frequency Drives (2, 4, 6 pole)

Premium efficient motors without INVERTER GRADE insulation meet minimum NEMA®† MG-1, Section IV, Part 31.4.4.2. These motors can be used with Variable Frequency Drives (with a reduced warranty period) under the following parameters:

- On NEMA®† frame 447 and smaller motors, 20:1 speed rating on variable torque loads & 4:1 speed range on constant torque loads.
- On TITAN® 449 and larger frame motors, 10:1 speed rating on variable torque loads.

 On TITAN® frame motors, inquiry required for suitability on constant torque loads.

Cable distances are for reference only and can be further limited by hot and humid environments (refer to Table 1). Refer to specific VFD

Table 1 - Cable Distances								
Maximum Cable Distance VFD to Motor								
Switching Frequency	460 Volt	230 Volt	380 Volt					
3 Khz	127 ft	400 ft	218 ft					
6 Khz	90 ft	307 ft	154 ft					
9 Khz	73 ft	251 ft	126 ft					
12 Khz	64 ft	217 ft	109 ft					
15 Khz	57 ft	194 ft	98 ft					
20 Khz	49 ft	168 ft	85 ft					

manufacturers cable limits. Refer to the Motor/ Inverter Compatibility page for special consideration of vertical motor bearings.

Warranty Period Clarifications and Exceptions

Standard Energy Efficient Exclusion

Applying Standard & Energy Efficient Motors on Variable Frequency Drives is not recommended. VFD related failures on standard and energy efficient motors will not be covered under warranty.

Vertical Motor Windings

Premium efficient vertical motors without INVERTER GRADE® insulation that are installed using the criteria described in this document and applied in the correct applications shall have a warranty while powered by a VFD for 12 months from date of installation or 18 months from date of manufacturing whichever comes first. See limited warranty page for horizontal motor warranty periods.

Bearing Exclusion for Thrust Handling Bearings

Bearings used in premium efficienct vertical motors, and all thrust handling bearings, that are powered by VFDs without shaft grounding devices or insulated bearings (when required) will not be covered under any warranty for damages caused from being powered by a VFD. All other bearing failure is covered per NMC's standard warranty. An electric motor repair shop approved to service U.S. MOTORS® brand motors must verify that the cause of the bearing failure was not due to Electrical Discharge Machining.

Medium Voltage and Slow Speed Considerations

Motors that are rated above 700 VAC or that are eight pole and slower require special consideration and installation and are not covered under the warranty guidelines in this document. Motors that are rated above 700VAC have special cable length and voltage differential issues that are specific to the VFD type and manufacture. The motor construction and cost may vary dramatically depending on the VFD topology and construction. Contact your NMC representative with VFD manufacturer name and model type for application and motor construction considerations. Motors that are designed eight pole and slower also require special installation and filters per the drive manufacturer.

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^{*} This information applies only to Integral Horsepower (IHP) motors as defined on the Agency Approval page, under UL* & CSA* listings where indicated.