NIDEC MOTOR CORPORATION

8050 WEST FLORISSANT AVE. ST. LOUIS, MO 63136

DATE: 4/20/2022

TO:

P.O. NO.: DT94 Order/Line NO.: 22252 MN 100

Model Number:DT94Catalog Number:HO50V2BLGVHS Weather ProtectedCONF,MOTOR,VHS WPI

REVISIONS: (NONE)

ALL DOCUMENTS HEREIN ARE CONSIDERED CERTIFIED BY NIDEC MOTOR CORPORATION. THANK YOU FOR YOUR ORDER AND THE OPPORTUNITY TO SERVE YOU.

Features:

Horsepower 00050.00~00000.00 ~ KW: 37.3 Enclosure WPI Poles 04~00 ~ RPM: 1800~0 Frame Size 326~TP Phase/Frequency/Voltage.. 3~060~230/460 ~ Random Wound Service Factor 1.15 Insulation Class Class "F" ~ Insulife 2000 Altitude In Feet (Max) .. 3300 Ft.(1000 M) ~ +40 C Efficiency Class Premium Efficiency Application Vertical Centrifugal Pump Inverter Duty NEMA MG1 Part 31 Customer Part Number 16.5" Base ~ Coupling Size: 1-1/4" Bore, 1/4" Key Non-Reverse Ratchet ~ Steady Bushing Not Requested Pricebook Thrust Value (lbs).. 5700 Customer Down Thrust (lbs) ... 5700 Customer Shutoff Thrust (lbs). Up Thrust (lbs): ~ Inverter Duty Rating Details: Load Type (Base Hz & Below) .. Variable Torque Speed Range (Base Hz & Below). 10:1 Temperature Rise (Sine Wave): "F" Rise @ SF (Resist) NEMA Design B Starting Method PWS (Dual Volt-Low Volt Only) Duty Cycle Continuous Duty Efficiency Value 94.5 % ~ Typical Load Inertia (lb-ft2): NEMA ~ NEMA Inertia: 232.00 ~ 1.00 Number Of Starts Per Hour: NEMA Motor Type Code RUSI Rotor Inertia (LB-FT²) 8.69 LB-FT² Qty. of Bearings PE (Shaft) 1 Qty. of Bearings SE (OPP) 1 Bearing Number PE (Shaft) 6211-J Bearing Number SE (OPP) 7220 BEP

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Accessories:

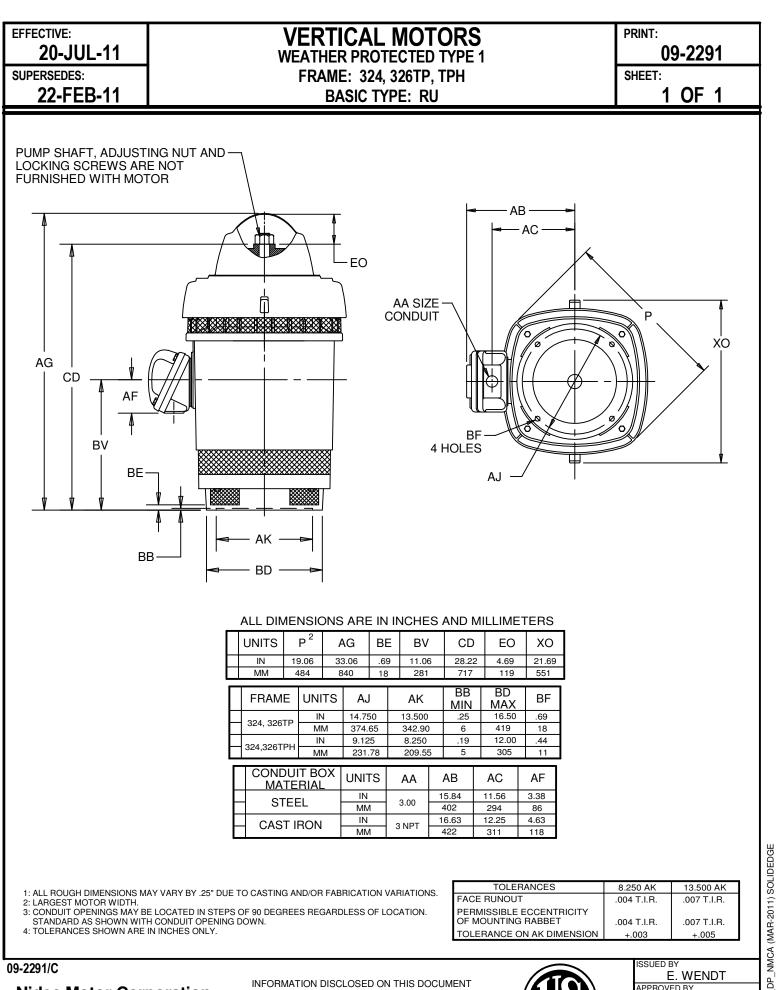
Counter CW Rotation FODE Shaft Ground Ring 115 Volt Space Heaters Special Balance Thermostats - Normally Closed Standard Leadtime: NA Est. Weight (lbs ea): 675 ~ F.O.B.:

USE THE DATA PROVIDED BELOW TO SELECT THE APPROPRIATE DIMENSION PRINT

Horsepower	50
Pole(s)	04
Voltage(s)	460-230
Frame Size	326TP
Outlet Box AF	3.38
Outlet Box AA	3.00

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3: CONDUIT OPENINGS MAY BE LOCATED IN STEPS OF 90 DEGREES REGARDLESS OF LOCATION.

STANDARD AS SHOWN WITH CONDUIT OPENING DOWN.

4:	TOLERANCES	SHOWN ARE IN	INCHES	ONLY.

TOLERANCES	8.250 AK	13.500 AK
FACE RUNOUT	.004 T.I.R.	.007 T.I.R.
PERMISSIBLE ECCENTRICITY OF MOUNTING RABBET	.004 T.I.R.	.007 T.I.R.
TOLERANCE ON AK DIMENSION	+.003	+.005

09-2291/C

Nidec Motor Corporation St. Louis, Missouri

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ISSUED BY E. WENDT APPROVED BY K. POTTER

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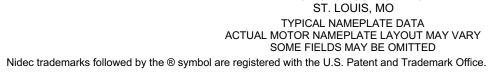
NAMEPLATE DATA

CATALOG NUM	BER:	НО	50V2BLG	NAMEPLAT	E PART #:	4227	07-005
MODEL	DT94	FR	326TP	TYPE	RUSI	ENCL	WPI
SHAFT END BRG		6211	I-J - QTY 1	OF END		7220 BE	P - QTY 1
PH 3			С	ID#			
INSUL CLASS	As Po	m			DUTY	CONT	[]
HP 50		RPM	1780	HP 📼		RPM 📼	
VOLTS 460	23	0		VOLTS 📼			
FL 57.0	11:	3.0		FL AMPS			
SF 65.0	13	1.0		SF AMPS			
SF 1.1	15 DESIG	N B	CODE G	SF			CODE 📃
NEMA NOM EFFICIENCY 94	.5 NOM	1 87.7	KiloWatt 37.3	NEMA NOM EFFICIENCY	NON PF		
GUARANTEED	6 MAX		HZ 60	GUARANTEED EFFICIENCY	MAX KVA		HZ
	KVAr						
HAZARDOUS LOCATION DIVISION	N DATA (IF AI	PPLICABLE):	CLASS I		GRO		
TEMP CODE			CLASS II		GROU]
					(
						NEM	
					SP	Premiu	467542
VFD DATA (IF APPLICAE	BLE):						
VOLTS	460)	230	AMPS	59.	9	118.7
TORQUE 1	[147	.5LB-FT	TORQU	JE 2		
VFD LOAD TYP	PE 1	V	ſ/PWM	VFD LOAD	TYPE 2		
VFD HERTZ RAN	IGE 1		6-60	VFD HERTZ	RANGE 2		
VFD SPEED RAN	IGE 1	18	0-1800	VFD SPEED	RANGE 2		
	г						
SERVICE FACT	L		1.00	FL SL			
NO. POLES VECTOR MAX F				MAGNETIZII Encoder			
Radians / Seco	nds I]	Encoder	Volts		
TEAO DATA (IF APPLIC	ABLE):						
HP (AIR OVER)		HP (AIR OVE M/S)	R	RPM (AIR OVER)]	RPM (AIR OVER M/S)	
FPM AIR VELOCITY		FPM AIR	/S	FPM AIR VELOCITY SEC	1		
12200111			-				

ADDITIONAL NAMEPLATE DATA:

	ADDITIONAL N	AMEPLATE DATA:	
Decal / Plate	WD=159833,CP=132839	Customer PN	
Notes		Non Rev Ratchet	NRR
Max Temp Rise		OPP/Upper Oil Cap	3 QT/2.8 L
Thermal (WDG)	OVER TEMP PROT 2	SHAFT/Lower Oil Cap	GREASE
Altitude		Usable At	
Regulatory Notes		Regulatory Compliance	
COS		Marine Duty	
Balance	0.08 IN/SEC	Arctic Duty	
3/4 Load Eff.	94.6	Inrush Limit	
Motor Weight (LBS)	675	Direction of Rotation	
Sound Level		Special Note 1	
Vertical Thrust (LBS)	5700	Special Note 2	
Thrust Percentage	100% HT	Special Note 3	
Bearing Life		Special Note 4	
Starting Method		Special Note 5	
Number of Starts		Special Note 6	
200/208V 60Hz Max Amps		SH Max. Temp.	
190V 50 hz Max Amps		SH Voltage	SH VOLTS=115V
380V 50 Hz Max Amps		SH Watts	SH WATTS= 96W
NEMA Inertia		Load Inertia	
Sumpheater Voltage		Sumpheater Wattage	
Special Accessory Note 1		Special Accessory Note 16	
Special Accessory Note 2		Special Accessory Note 17	
Special Accessory Note 3		Special Accessory Note 18	
Special Accessory Note 4		Special Accessory Note 19	
Special Accessory Note 5		Special Accessory Note 20	
Special Accessory Note 6		Special Accessory Note 21	
Special Accessory Note 7		Special Accessory Note 22	
Special Accessory Note 8		Special Accessory Note 23	
Special Accessory Note 9		Special Accessory Note 24	
Special Accessory Note 10		Special Accessory Note 25	
Special Accessory Note 11		Special Accessory Note 26	
Special Accessory Note 12		Special Accessory Note 27	
Special Accessory Note 13		Special Accessory Note 28	
Special Accessory Note 14		Special Accessory Note 29	
Special Accessory Note 15		Special Accessory Note 30	
Heater in C/B Voltage		Heater in C/B Watts	
Zone 2 Group		Division 2 Service Factor	
Note 1		Note 2	
Note 3		Note 4	
Note 5		Note 6	
Note 7		Note 8	
Note 9		Note 10	
Note 11		Note 12	
Note 13		Note 14	
Note 15		Note 16	
Note 17		Note 18	
Note 19		Note 20	
Note 21		Note 22	

NIDEC MOTOR CORPORATION





MOTOR PERFORMANCE

MODEL NO.	CATALOG NO.	PHASE	TYPE	FRAME
DT94	HO50V2BLG	3	RUSI	326TP
ORD	ER NO.	22252	LINE	NO.
MPI:			232462	232463
HP:			50	50
POLES:			4	4
VOLTS:			460	230
HZ:			60	60
SERVICE FACTO	R:		1.15	1.15
EFFICIENCY (%):				
	S.F.		93.9	93.9
	FULL		94.1	94.1
	3/4		94.6	94.6
	1/2		94.1	94.1
	1/4		90.9	90.9
POWER FACTOR	R (%):			
	S.F.		87.8	87.8
	FULL		87.7	87.7
	3/4		86.2	86.2
	1/2		80.9	80.9
	1/4		63.8	63.8
	NO LOAD		6.8	6.8
	LOCKED ROTO)R	37.2	37.2
AMPS:				
	S.F.		65	131
	FULL		57	113
	3/4		43	86
	1/2		31	61
	1/4		20.2	40
	NO LOAD		15	30
	LOCKED ROTO	DR	357	715
NEMA CODE LET			G	G
NEMA DESIGN L			В	В
FULL LOAD RPM			1780	1780
	/ EFFICIENCY (%)		94.5	94.5
GUARANTEED E	FFICIENCY (%)		93.6	93.6
MAX KVAR			10.2	10.2
AMBIENT (°C)			40	40
ALTITUDE (FASL	,		3300	3300
SAFE STALL TIM	· /		26	26
SOUND PRESSU	RE (DBA @ 1M)		65	65
TORQUES:				
	BREAKDOWN{%		251	251
	LOCKED ROTOR{		191	191
	FULL LOAD{LB-	FT}	147.5	147.5

NEMA Nominal and Guaranteed Efficiencies are up to 3,300 feet above sea level and 25 ° C ambient

The Above Data Is Typical, Sinewave Power Unless Noted Otherwise

NIDEC MOTOR CORPORATION ST. LOUIS, MO



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Motor Wiring Diagram

9 Lead, Dual Voltage, Delta Connection Part Winding Start (PWS) on Low Voltage

Part Wdg. Start	Run	Run
Low Volts Conn.	Low Volts Conn.	High Volts Conn.
$7 \bullet 8 \bullet 5 \bullet \\ 6 \bullet 4 \bullet 9 \bullet \\ 1 \bullet 2 \bullet 3 \bullet \\ 1 1 L2 L3$	$7 \bullet 8 \bullet 5 \bullet$ $6 \bullet 4 \bullet 9 \bullet$ $1 \bullet 2 \bullet 3 \bullet$ $L1 L2 L3$	$7 \bullet 8 \bullet \bullet 5$ $6 \bullet 4 \bullet 9 \bullet$ $1 \bullet 2 \bullet 3 \bullet$ $L1 L2 L3$

Motor good for across the line starting

Per NEMA MG1 1998-1.75, "A Part-winding Start motor is one which certain specially designed circuits of each phase of the primary winding are initially connected to the supply line. The remaining circuit or circuits of each phase are connected to the supply in parallel with initially connected circuits, at a predetermined point in the starting operation." This is intended to limit the inrush current required to start the motor. NEMA MG1 1998-14.38 states that the motor may not accelerate to full speed in part-winding and may be noisier than when on full winding.

Motors designed by US Motors for Part-winding Start also be used for across the line starting using only the full winding connection. Damage will occur if the motor is operated with load for more than 2 seconds on Part-winding without transition to full winding.

To reverse direction of rotation, interchange leads L1 & L2.

Each lead may have one or more cables comprising that lead. In such case, each cable will be marked with the appropriate lead number.



SPECIAL INFORMATION REGARDING PART WINDING STARTING

This motor is not designed to fully accelerate when started with the part winding start connection shown on the motor connection diagram. In order to avoid damaging the motor when it is started with the part winding start connection, set timers so that the motor starter switches the motor connection from start to run within two seconds from the time that the motor is initially energized. The motor is not expected to fully accelerate before the motor connection is switched to run, but the momentary operation on the start connection should allow time for automatic voltage regulators on the power system to compensate for voltage dip resulting from the high current draw of the motor during acceleration. Thus, voltage dip in the power system will be minimized through proper use of the part winding start connection. Once the motor has been switched over to the run connection, it will finish accelerating up to full speed.

During the time that the motor is operated on the part winding start connection, it is expected that the motor may be noisier than when operated on the run connection and it is also expected that the line amp unbalance between phases may be approximately 100% to 150%. This is due to the adverse effect of harmonics that result from the unbalanced magnetic circuit on the part winding start connection.

For further information regarding characteristics of polyphase induction motors when operated on a part winding start connection, refer to NEMA Publication MG 1-1998 Part 14.38.

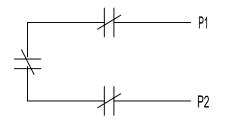
Connection Plate: 159833 Connection Decal: 344133 Revised: 02/07/12

THERMOSTATS

1. MOTOR IS EQUIPPED WITH QTY-3 (1 PER PHASE) NORMALLY CLOSED THERMOSTATS. THERMOSTATS ARE SET TO OPEN AT HIGH TEMPERATURE.

2. CONTACT RATINGS FOR THERMOSTATS: 120-600 VAC, 720 VA

N. C. THERMOSTATS



NOTE: THERMOSTATS LEADS MAY BE LOCATED IN EITHER THE MAIN OUTLET BOX OR IF SO EQUIPPED, AN AUXILIARY BOX.

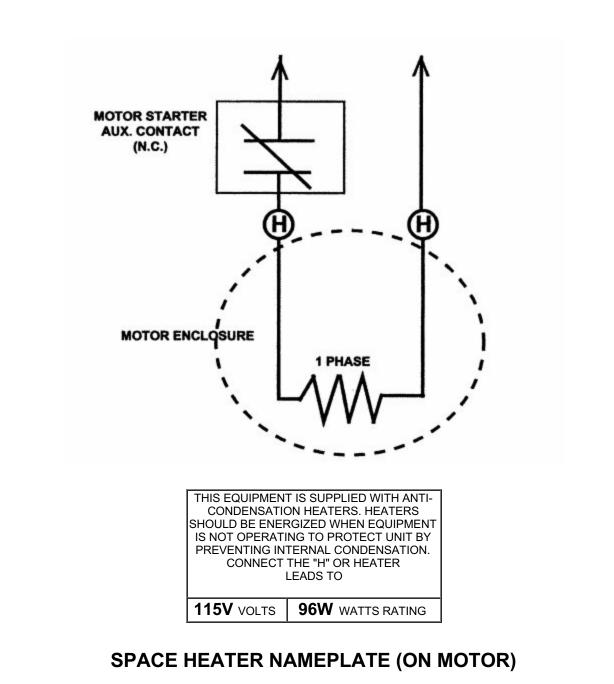
					ACCESSORY L	ISTING
					QTY-3 N.C. THERMO	STATS
	REVISION DESCRIPTION FOR: MISC STL0211 - UPDATED FORMAT .	NONE TOLERANCES C (UNLESS OTHER)	IN ON DIMENSIONS WISE SPECIFIED)		CUSTOMER	NIDEC MOTOR CORPORATION
	MATERIAL:	<u>INCHES</u>	<u>mm</u>	ISSUED BY R. K	APPROVED BY C. CADE	REVISION DATE 24-FEB-11
NIDEC CONFIDENTIAL NIDEC MOTOR CORPORATION 24-Feb-11	 MUST BE COMPLIANT TO RoHS DIRECTIVE EU 2002/95/IEC AND REGULATION EC 1907/2006 (REACH) AS AMENDED	ANGLES		CODE	DWG NO. 0834066	G 1 OF 1 A
NMCA (JAN-2011)						SOLIDEDGE





SPACE HEATER CONNECTION DIAGRAM

SPACE HEATER LEADS MAY BE LOCATED IN EITHER THE MAIN OUTLET BOX OR IF SO EQUIPPED, AN AUXILIARY BOX

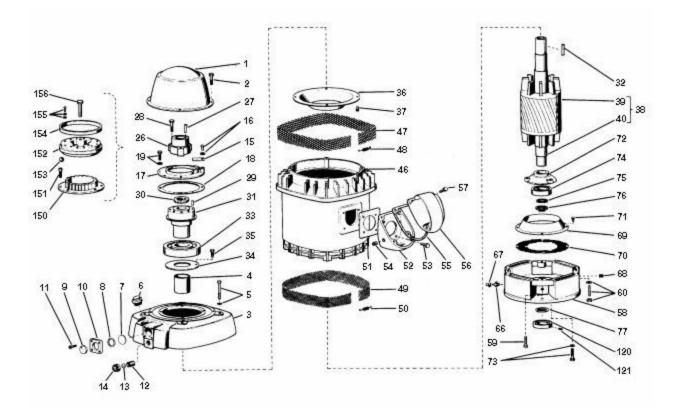


Revision: 7/30/2008 Mike Cullen

RENEWAL PARTS

FRAMES 324 THRU 447 - OPEN DRIPPROOF MOTORS TYPES: RU, RUE, RUI, RUS, RUSI, RV, RV4, RVE, RVE4, RVI, RVI4, RVS, RVS4

HIGH THRUST - WEATHER PROTECTED TYPE 1 - P BASE HOLLOSHAFT & SOLIDSHAFT MOTORS



BEARINGS:

bearing numbers.

ITEM NO.	QTY	NAME OF PART
1	1	Сапору Сар
2	3	Hex Head Cap Screws (Canopy Cap)
3	1	Upper Bracket Assembly
4	1	Oil Retaining Tube
5	4	Hex Head Cap Screw & Lockwasher (Bracket to Stator)
6	1	Special Plug
7	1	Reflector Disc
8	2	Gasket - Sight Gauge
9	1	Sight Gauge Window
10	1	Sight Gauge Housing
11	4	Oval Head Screw (Sight Gauge)
12	1	Nipple Fitting (Oil Drain)
13	1	Gasket or "O" Ring

ITEM NO.	QTY	NAME OF PART		
14	1	Drain Cap		
15	1	Locking Arm		
16	1	Hex Head Cap Screw & Lockwasher		
17	1	Dust Ring		
18	1	Gasket (Dust Ring)		
19	3	Hex Head Cap Screw & Lockwasher		
20-25	-	NOT USED THIS ASSEMBLY		
26	1	Coupling (RU & RUE only)		
27	1	Gib Key		
28	3	Hex Head Cap Screw & Lockwasher (Bearing Mounting)		
29	3	Spring Pin		
30	1	Locknut / Lockwasher		

WARNING:

Any disassembly or repair work on explosionproof motors will void the Underwriters Laboratories, Inc.label unless done by the manufacturer, or a facility approved by the Underwriters Laboratories, Inc.Refer to your nearest sales office for assistance.

Refer to motor nameplate for the

Parts stocking distributors: refer to renewal parts numerical index.All Others: refer to your nearest parts distributor.

reference: Renewal Parts Section 700, Pages 149 & 150

PRICES:

RENEWAL PARTS

FRAMES 324 THRU 447 - OPEN DRIPPROOF MOTORS TYPES: RU, RUE, RUI, RUS, RUSI, RV, RV4, RVE, RVE4, RVI, RVI4, RVS, RVS4

HIGH THRUST - WEATHER PROTECTED TYPE 1 - P BASE HOLLOSHAFT & SOLIDSHAFT MOTORS

ITEM NO.	QTY	NAME OF PART		
31	1	Bearing Mounting		
32	1	Square Key		
33	1	Ball Bearing (Upper) (Refer to Section 775)		
34	1	Metering Plate (Used on 444 & 445 frames only)		
35	1	Hex Head Cap Screw & Lockwasher (Used on 444 & 445 frames only)		
36	1	Air Deflector (Upper)		
37	7	Self-Tapping Screw (Air Deflector) Use Qty. 8 on 404 & 405 frame & Qty. 6 on 444 & 445 frame		
38	1	Rotor Assembly (Includes items 39 & 40)		
39	1	Rotor Core		
40	1	Rotor Shaft		
41-45	-	NOT USED THIS ASSEMBLY		
46	1	Wound Stator Assembly		
47	1	Grill (Upper Fame)		
48	1	Expansion Spring		
49	1	Grill (Lower Frame)		
50	1	xpansion Spring		
51	1	Gasket (Outlet Box Base)		
52	1	Outlet Box Base		
53	4	Hex Head Cap Screw		
54	1	Hex Head Countersunk Pipe Plug		
55	1	Gasket (Outlet Box Cover)		
56	1	Outlet Box Cover		
57	4	Hex Head Cap Screw (Outlet Box Cover)		
58	1	Lower Bracket "P" Base		
59	4	Hex Head Cap Screw (Not used on 404 & 405 frames)		
60	4	Stud / Nut & Washer (Used on 404 & 405 frames only)		

ITEM NO.	QTY	NAME OF PART
61-65	-	NOT USED THIS ASSEMBLY
66	1	Grease Fitting
67	1	Plastic Cap (Used on frames 404, 405, 444 & 445 only)
68	1	Pipe Plug
69	1	Lower Air Deflector
70	1	Lower Screen
71	4	Hex Head Cap Screw & Lockwasher (Qty. 8 on 404 & 405 frames, Qty. 6 on 444 & 445 frames)
72	1	Lower Bearing Cap
73	3	Hex Head Cap Screw / Lockwasher
74	1	Ball Bearing (Lower) (Refer to Section 775)
75	1	Bearing Spacer (Lower)
76	1	Snap Ring
77	1	Water Deflector
		FOR UNITS WITH STABILIZER BUSHINGS, OMIT ITEM NO. 77 & ADD THE FOLLOWING:
120	1	Stabilizer Bushing
121 2 Socket Set Screws		Socket Set Screws
	OMI	FOR UNITS WITH NON-REVERESE RATCHETS, T ITEM NO.'s 15, 17 & 19 AND ADD THE FOLLOWING:
150	1	Stationary Ratchet
151	3	Socket Head Cap Screws
152	1	Rotating Ratchet
153	12	Steel Balls
154	1	Ball Retaining Ring
155	6	Round Head Machine Screws, Lockwasher & Plain Washers
156	3	Hex Head Cap Screws

WARNING: Any disassembly or repair work on explosionproof motors will void the Underwriters Laboratories, Inc. label unless done by the manufacturer, or a facility approved by the Underwriters Laboratories, Inc. Refer to your nearest sales office for assistance.

BEARINGS: Refer to motor nameplate for the bearing numbers.

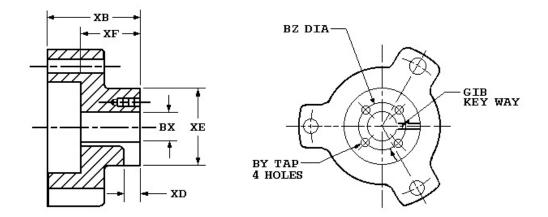
PRICES: Parts stocking distributors: refer to renewal parts numerical index. All Others: refer to your nearest parts distributor.

reference: Renewal Parts Section 700, Pages 149 & 150

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Vertical HOLLOSHAFT Coupling Dimensions

Standard Coupling Dimensions



Coupling Part Number	162458
BX Nominal	1 1/4
Actual Bore	1.251
BY	1/4-20
BZ	1 3/4
ХВ	2 15/16
XD	17/32
XE	2 7/8
XF	1 15/16
SQ. KEY	1/4

Notes:

- 1. All Rough casting dimensions may vary by 0.25" due to casting variations.
- 2. All tapped holes are Unified National Course, Right Hand thread.
- 3. Coupling bore dimension "BX" is machined with a tolerance of .000", +.001" up to 1.50" bore inclusive. Larger bores: -.000", +.002".



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TYPICAL REED CRITICAL FREQUENCY DATA

<u>Note</u>: Motor RCF Test Data can be provided at time of motor shipment through special test. Please contact your Nidec Motor Corporation representative for more information.

> MODEL NO: DT94 CATALOG NO: HO50V2BLG

Frame: 326TP Type: RUSI

REED CRITICAL FREQUENCY:		ΗZ
CENTER OF GRAVITY:	13	IN
DEFLECTION @ CENTER OF GRAVITY:	0.00301	IN
UNIT WEIGHT:	690	LBS
BASE DIAMETER:	ALL	IN
TOLERANCE ON RCF VALUE:	10%	
DATE:	4/20/2022	



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General Information for Integral Horsepower (IHP) Motors on Variable Frequency Drives (VFDs)

Variable Frequency Drives (VFD)

A VFD is a type of controller used to vary the speed of an electric motor. The VFD takes a fixed AC voltage and frequency and allows it to be adjusted in order to get different speeds from the motor. Motor speed can be varied by changing the frequency of the input power waveform. The equation below shows how the frequency affects the speed of a three phase induction motor.

> Speed = <u>
> 120* Fundamental Input Frequency</u> Number of Motor Poles

How does a VFD work?

A VFD takes the fixed frequency and voltage sine wave from the power grid or power station and puts it through a few steps in order to allow the VFD user to vary the frequency and in turn control the motor speed. First it rectifies the AC power into DC Power. Because of this step, a term commonly used instead of VFD is inverter. This only describes one step of what the VFD does to the power waveform. Once rectified into a DC voltage the drive sends the power through a set of transistors or switches. These switches can take the DC waveform and by opening and closing at certain speeds and durations can create an output waveform that mimics the sine wave that is required to drive a three phase electric motor. The output waveform is known as a Pulse Width Modulation (PWM) waveform because the waveform is created by multiple pulses of the switches at short intervals.





What variables should be considered when deciding whether to power a motor with a VFD?

VFD compatibility with motors is complex. As a result, many variables must be considered when determining the suitability of a particular motor for use with a VFD. These variables include:

- Torque requirements (Constant or Variable)
- Speed Range
- Line / System Voltage
- Cable length between the VFD and the motor
- Drive switching (carrier) frequency
- Motor construction

- VFD dv/dt winding end turn differential in voltage versus differential in time
- · High temperatures or high humidity
- Grouding system

Wider speed ranges, higher voltages, higher switching frequencies, insufficient grounding and increased cable lengths all add to the severity of the application and, therefore, the potential for premature motor failure.

How does a VFD affect the motor?

There are many things to consider when a motor is powered using a VFD or PWM power. When a motor is powered by a PWM waveform the motor windings very often see a large differential voltage, either from phase to phase or turn to turn. When the voltage differential becomes large enough it creates a reaction at the molecular level that converts available oxygen into O3. This phenomenon is called partial discharge or corona. This reaction creates energy in the form of light and heat. This energy has a corrosive effect on the varnish used to protect the motor windings. PWM waveforms can also magnify shaft voltages which lead to arcing across the bearing and causing premature bearing failure. Corrective action must be taken to mitigate these issues that arise when using an electric motor with a VFD.

How do I protect the motor?

Nidec Motor Corporation (NMC) has developed specific motor designs to decrease the harmful affects that a VFD can have on a motor. NMC's INVERTER GRADE® insulation system is the first line of defense against corona and phase to phase faults that can be common when a motor is powered using a PWM waveform. The INVERTER GRADE® insulation system is standard on all of NMC's Inverter Duty products. Along with the INVERTER GRADE® insulation, thermostats are installed as a minimum protection against over heating the motor. Special consideration must also be given to bearings in motors powered by VFD's. In order to create a low resistance path to ground for built up shaft voltages a shaft grounding device can be used. On larger horsepower motors an insulated bearing system should be used in conjunction with the shaft grounding device when installed, to force the stray shaft voltages to ground. The bearing failures are more prominent on motors with thrust handling bearings. NMC has created an Inverter Duty vertical motor line that not only uses the INVERTER GRADE® insulation system, but that also comes standard with a shaft grounding device. On motors that are 100 HP and greater the thrust bearing is also insulated for additional protection.

What does "Inverter Duty" mean?

An Inverter Duty motor should describe a motor that helps mitigate potential failure modes of a motor that is powered by a VFD. Inverter duty motor windings should be able to withstand the voltage spikes per NEMA MG1 Part 31.4.4.2 and protect against overheating when the motor is run at slow speeds. On thrust handling bearings it is apparent that the bearings require additional protection. Inverter Duty vertical motors should have a shaft grounding device to protect the motor bearings from fluting due to voltage discharge through the bearing. On larger motors (100HP and larger) the shaft should also be electrically isolated from the frame in order to aid the shaft grounding ring in discharging the shaft voltages to ground.

*This information applies only to Integral Horsepower (IHP) motors as defined on the Agency Approval page, under UL®t & CSA®t listings where indicated.

Thermal Overloads and Single Phase Motors

Motors with thermal overloads installed may not operate properly on a VFD. The current carrying thermal overload is designed for sine wave power. Operation on a VFD may cause nuisance tripping or potentially not protect the motor as would be expected on line power. Thermostats or thermistors installed in the motor and connected properly to the VFD may provide suitable thermal overload protection when operating on a VFD. (consult codes for installation requirements)

Single phase motors and other fractional horsepower ratings are not designed to be operated on a VFD. Within Nidec Motor Corporation standard products, all motors NEMA®r 48 frame (5.5" diameter) and smaller are not suitable for VFD applications. Three phase 56 and 143/145 frame applications should be noted on the catalog price page; or if in doubt ask a Nidec Motor Corporation technical representative for recommendations on compatibility with a VFD.

Slow Speed Motors

Motors with a base design of slower than six poles require special consideration regarding VFD sizing and minimizing harmonic distortion created at the motor terminals due to cable installation characteristics. Additional external PWM waveform filters and shielded motor cables designed for PWM power may be required to provide acceptable motor life. Harmonic distortion on the output waveform should be kept to a minimum level (less than 10%) mismatch impedance.

690V Applications

Motors that are rated for 690VAC and that will be powered by 690VAC PWM VFDs require the use of an external filter to limit peak voltage spikes and the use of an INVERTER GRADE® motor. Where available, an alternative to using an output filter is to upgrade to a 2300V insulation system.

Low Voltage TITAN[®] Motors

When using 449 frame and larger motors on PWM type VFDs consider the use of an external filter and shielded motor cables designed for PWM power to minimize harmonic distortion and peak voltages at the motor terminals. Harmonic distortion on the output waveform should be kept to a minimum level (less than 10%).

Bearing Currents Related to PWM Waveforms

Protection of the motor bearings from shaft currents caused by common mode voltages is becoming a standard feature on Inverter Duty motor products. Some installations may be prone to a voltage discharge condition through the motor bearings called Electrical Discharge Machining (EDM) or fluting. Vertical HOLLOSHAFT and HOSTILE DUTY World Motor come with grounding devices installed as standard. EDM damage is related to characteristics of the PWM waveform, and the VFD programming, and installations factors.

Bearing Protection on Inverter Duty Vertical Motors

All U.S. MOTORS® brand "Inverter Duty" vertical products have a shaft grounding system that allows damaging shaft currents a low resistance path to ground. **Bearings on vertical motors fed by VFD power without this bearing protection are not covered under any warranty.** All other bearing failure is covered per NMC's standard warranty. An electric motor repair shop approved to service U.S. MOTORS® brand motors must verify that the cause of the bearing failure was not due to EDM damage.

Guideline For Insulated Anti-Friction Bearings

Bearing insulation is required to prevent circulating shaft currents which can damage bearings. Circulating shaft current can be caused by use of improper power and/or ground cables, improper grounding systems and higher switching frequencies. Finding and correcting the external condition(s) is the responsibility of the system designer or specifying engineer. To prevent circulating shaft current in motors with anti-friction bearings, Nidec Motor Corporation's standard practice is to insulate the non-drive end bearing.

Adjustable Speed Drives produce a common mode voltage condition. To interrupt common mode voltage on induction motors of all sizes, NEMA MG1-2018 Part 31 recommends insulating both bearings. In cases where both anti-friction bearings are insulated, the system designer or specifying engineer should determine whether to apply one or more of the following options to prevent or reduce shaft currents: sinewave filters, line reactors or mechanical devices, such as shaft grounding or an insulated half coupling. Motors with shaft grounding devices are not suitable for installation in hazardous locations unless housed in an enclosure suitable for the specified Division (or Zone), Class and Group(s).

Multiple Motors on a Single VFD

Special considerations are required when multiple motors are powered from a single VFD unit. Most VFD manufacturers can provide guidelines for proper motor thermal considerations and starting/stopping of motors. Cable runs from the VFD and each motor can create conditions that will cause extra stress on the motor winding. Filters may be required at the motor to provide maximum motor life.

Grounding and Cable Installation Guidelines

Proper output winding and grounding practices can be instrumental in minimizing motor related failures caused by PWM waveform characteristics and installation factors. VFD manufacturers typically provide detailed guidelines on the proper grounding of the motor to the VFD and output cable routing. Cabling manufacturers provide recommended cable types for PWM installations and critical information concerning output wiring impedance and capacitance to ground.

Integrated Motor and Inverter

By integrating the motor and inverter at NMC's manufacturing facility, many of the motor compatibility problems are minimized or eliminated. During the manufacturing process, the motor is matched to the inverter characteristics which ensures the winding temperature and torque levels meet the design specification. Since the inverter output wring to the motor is nearly eliminated, bearing currents are rarely experienced. When the unit is properly grounded, reducing the output cable lengths in conjunction with an inverter grade insulation system and low factory setting of the switching frequency of the inverter drive, results in low risk of voltage peaks produced by the PWM waveform.

Vertical Motors on VFDs

Vertical motors operated on VFD power present unique conditions that may require consideration by the user or installation engineer:

- Locked rotor and drive tripping caused by non-reversing-ratchet operation at low motor speeds. It is not recommended to operate motors at less than 1/4 of synchronous speed. If slow speeds are required contact NMC engineering.
- Unexpected / unacceptable system vibration and or noise levels caused by the torque pulsation characteristics of the PWM waveform, a system critical frequency falling inside the variable speed range of the process or the added harmonic content of the PWM waveform exciting a system component
- Application related problems related to the controlled acceleration/deceleration and torque of the motor on VFD power and the building of system pressure/ load.
- The impact the reduction of pump speed has on the down thrust reflected to the pump motor and any minimum thrust requirements of the motor bearings
- · Water hammer during shutdown damaging the non-reversing ratchet

Humidity and Non-operational Conditions

The possible build-up of condensation inside the motor due to storage in an uncontrolled environment or non-operational periods in an installation, can lead to an increased rate of premature winding or bearing failures when combined with the stresses associated with PWM waveform characteristics. Moisture and condensation in and on the motor winding over time can provide tracking paths to ground, lower the resistance of the motor winding to ground, and lower the Corona Inception Voltage (CIV) level of the winding.

Proper storage and maintenance guidelines are important to minimize the potential of premature failures. Space heaters or trickle voltage heating methods are the common methods for drying out a winding that has low resistance readings. Damage caused by these factors are not covered by the limited warranty provided for the motor unless appropriate heating methods are properly utilized during non-operational periods and prior to motor start-up.

NEMA® Application Guide for AC Adjustable Speed Drive Systems: http://www. nema.org/stds/acadjustable.cfm#download

* This information applies only to Integral Horsepower (IHP) motors as defined on the Agency Approval page, under UL* & CSA* listings where indicated.

Warranty Guidelines

The information in the following section refers to the motor and drive application guidelines and limitations for warranty.

Hazardous Location Motors

Use of a variable frequency drive with the motors in this catalog, intended for use in hazardous locations, is only approved for Division1, Class I, Group D hazardous location motors with a T2B temperature code, with a limitation of 2:1 constant torque or 10:1 variable torque output. **No** other stock hazardous location motors are inherently suitable for operation with a variable frequency drive. If other requirements are needed, including non-listed Division 2, please contact your Nidec Motor Corporation territory manager to conduct an engineering inquiry.

575 Volt Motors

575 volt motors can be applied on Inverters when output filters are used. Contact the drive manufacturer for filter selection and installation requirements.

Applying INVERTER GRADE[®] Insulated Motors on Variable Frequency Drives (2, 4, 6 pole)

The products within this catalog labeled "Inverter Duty" or "Vector Duty" are considered INVERTER GRADE[®] insulated motors. INVERTER GRADE[®] motors exceed the NEMA^{®†} MG-1 Part 31 standard. Nidec Motor Corporation provides a three-year limited warranty on all NEMA^{®†} frame INVERTER GRADE[®] insulated motors and allows long cable runs between the motor and the VFD (limited to 400 feet without output filters). Cable distance can be further limited by hot and humid environments and VFD manufacturers cable limits. These motors may be appropriate for certain severe inverter applications or when the factors relating to the end use application are undefined (such as spares).

Nidec Motor Corporation's U.S. Motors® brand is available in the following INVERTER GRADE® insulated motors:

- Inverter Duty NEMA^{®†} frame motors good for 20:1 Variable Torque & 5:1 Constant Torque, including Vertical Type RUSI (10:1 V.T.)
- Inverter Duty motors rated for 20:1 Constant Torque
- \bullet ACCU-Torq $^{\otimes}$ and Vector Duty Motors with full torque to 0 Speed or 5000:1
- 841 Plus® NEMA®† Frame Motors

Applying Premium Efficient motors (that do not have INVERTER $GRADE^{\otimes}$ insulation) on Variable Frequency Drives (2, 4, 6 pole)

Premium efficient motors without INVERTER GRADE insulation meet minimum NEMA®⁺ MG-1, Section IV, Part 31.4.4.2. These motors can be used with Variable Frequency Drives (with a reduced warranty period) under the following parameters:

- On NEMA®[†] frame 447 and smaller motors, 20:1 speed rating on variable torque loads & 4:1 speed range on constant torque loads.
- On TITAN $^{\otimes}$ 449 and larger frame motors, 10:1 speed rating on variable torque loads.

 On TITAN[®] frame motors, inquiry required for suitability on constant torque loads.

Cable distances are for reference only and can be further limited by hot and humid environments (refer to Table 1). Refer to specific VFD

Table 1 - Cable Distances				
Maximum Cable Distance VFD to Motor				
Switching Frequency	460 Volt	230 Volt	380 Volt	
3 Khz	127 ft	400 ft	218 ft	
6 Khz	90 ft	307 ft	154 ft	
9 Khz	73 ft	251 ft	126 ft	
12 Khz	64 ft	217 ft	109 ft	
15 Khz	57 ft	194 ft	98 ft	
20 Khz	49 ft	168 ft	85 ft	

manufacturers cable limits. Refer to the Motor/ Inverter Compatibility page for special consideration of vertical motor bearings.

Warranty Period Clarifications and Exceptions

Standard Energy Efficient Exclusion

Applying Standard & Energy Efficient Motors on Variable Frequency Drives is not recommended. VFD related failures on standard and energy efficient motors will not be covered under warranty.

Vertical Motor Windings

Premium efficient vertical motors without INVERTER GRADE[®] insulation that are installed using the criteria described in this document and applied in the correct applications shall have a warranty while powered by a VFD for 12 months from date of installation or 18 months from date of manufacturing whichever comes first. See limited warranty page for horizontal motor warranty periods.

Bearing Exclusion for Thrust Handling Bearings

Bearings used in premium efficienct vertical motors, and all thrust handling bearings, that are powered by VFDs without shaft grounding devices or insulated bearings (when required) will not be covered under any warranty for damages caused from being powered by a VFD. All other bearing failure is covered per NMC's standard warranty. An electric motor repair shop approved to service U.S. MOTORS[®] brand motors must verify that the cause of the bearing failure was not due to Electrical Discharge Machining.

Medium Voltage and Slow Speed Considerations

Motors that are rated above 700 VAC or that are eight pole and slower require special consideration and installation and are not covered under the warranty guidelines in this document. Motors that are rated above 700VAC have special cable length and voltage differential issues that are specific to the VFD type and manufacture. The motor construction and cost may vary dramatically depending on the VFD topology and construction. Contact your NMC representative with VFD manufacturer name and model type for application and motor construction considerations. Motors that are designed eight pole and slower also require special installation and filters per the drive manufacturer.

* This information applies only to Integral Horsepower (IHP) motors as defined on the Agency Approval page, under UL*+ & CSA*+ listings where indicated.